

DC/DC converter

Input 36-75 Vdc
Output up to 40A/100W

Key Features

- Industry standard Half-brick
58x61x8.5 mm (2.3x2.4x0.33 in)
- Low profile, max 8.5 mm (0.33 in)
- High efficiency, typ. 93 % at 3.3 Vout
half load
- 1500 VDC input to output isolation,
meets isolation requirements equivalent
to Basic Insulation according to
IEC/EN/UL 60950
- More than 6 million hours predicted
MTBF at 55° C ambient and 1 m/s
(200 lfm) airflow



Safety Approvals

Design for Environment



RoHS
compatible



The PKJ 4000E series of high efficiency DC/DC converters are designed to provide high quality on-board power solutions in distributed power architectures used in Internetworking equipment in wireless and wired communications applications.

The PKJ 4000E series has industry standard half brick footprint and pin-out and is only 8.5 mm (0.33 in) high. This makes it extremely well suited for narrow board pitch applications with board spacing down to 15 mm (0.6 in). The PKJ 4000E series uses patented synchronous rectification technology and achieves an efficiency up to 89% at full load. Ericsson's PKJ 4000E series addresses the emerging telecom market for applications in the multi-

service network by specifying the input voltage range in accordance with ETSI specifications.

Included as standard features are output over-voltage protection, input under-voltage protection, over temperature protection, soft-start, output short circuit protection, remote sense, remote control, and output voltage adjust function.

These converters are designed to meet high reliability requirements and are manufactured in highly automated manufacturing lines and meet world-class quality levels. Ericsson Power Modules is an ISO 9001/14001 certified supplier.

Absolute Maximum Ratings

| Characteristics | | min | max | Unit |
|-----------------|--|------|-------------------|------|
| T_{Pcb} | Maximum Operating Pcb Temperature | -40 | +125 | °C |
| T_S | Storage temperature | -55 | +125 | °C |
| V_I | Input voltage | -0.5 | +80 | Vdc |
| V_{ISO} | Isolation voltage (input to output test voltage) | | 1500 | Vdc |
| V_{tr} | Input voltage transient for 100 ms | | 100 | Vdc |
| V_{RC} | Negative logic | | 75 | Vdc |
| V_{RC} | Positive logic | | 6 | Vdc |
| V_{adj} | Maximum input | -0.5 | $2 \times V_{oi}$ | Vdc |

Note:

Stress in excess of Absolute Maximum Ratings may cause permanent damage. Absolute Maximum Ratings, sometimes referred to as no destruction limits, are normally tested with one parameter at a time exceeding the limits of Output data or Electrical Characteristics. If exposed to stress above these limits, function and performance may degrade in an unspecified manner.

Input $T_{Pcb} < T_{Pcb\ max}$ unless otherwise specified

| Characteristics | | Conditions | min | typ | max | Unit |
|-----------------|--|------------------------------|-----|------|-----|------------|
| V_I | Input voltage range | | 36 | | 75 | Vdc |
| V_{Ioff} | Turn-off input voltage | Ramping from higher voltage | | 32 | | Vdc |
| V_{Ion} | Turn-on input voltage | Ramping from lower voltage | | 34 | | Vdc |
| C_I | Input capacitance | | | 2 | | µF |
| I_{lac} | Reflected ripple current | 5 Hz to 20 MHz | | TBD | | mA_{p-p} |
| P_{II} | Input idling power | $I_o = 0, V_I = 53\ V$ | | 2 | | W |
| P_{RC} | Input standby power (turned off with RC) | $V_I = 53\ V, RC\ activated$ | | 0.25 | | W |

Environmental Characteristics

| Characteristics | | | |
|---------------------------------|-------------------------|--|---|
| Random Vibration | IEC 68-2-34 E_d | Frequency Spectral density Duration | 10 ... 500 Hz 0.07 g^2/Hz 10 min each direction |
| Sinusoidal Vibration | IEC 68-2-6 F_c | Frequency Amplitude Acceleration Number of cycles | 10 ... 500 Hz 0.75 mm 10 g 10 in each axis |
| Shock (half sinus) | IEC 68-2-27 E_a | Peak acceleration Duration | 100 g 6 ms |
| Temperature change | IEC 68-2-14 N_a | Temperature Number of cycles | -40 ... +100 °C 300 |
| Heat/Humidity | IEC 68-2-3 C_a | Temperature Humidity Duration | +85 °C 85 % RH 1000 hours |
| Solder heat stability | IEC 68-2-20 1A | Temperature, solder Duration | 260 °C 10 ... 13 s |
| Resistance to cleaning solvents | IEC 68-2-45 XA Method 2 | Water Isopropyl alcohol Glycol ether | +55 ± 5 °C +35 ± 5 °C +35 ± 5 °C |
| Cold (in operation) | IEC 68-2-1 A_d | Temperature Duration | -45 °C 2 h |
| Storage test | IEC 68-2-2 B_a | Temperature Duration | +125 °C 1000 h |

The PKJ 4000 E series DC/DC converters are designed in accordance with safety standards IEC/EN/UL 60950, *Safety of Information Technology Equipment*. The PKJ 4000 E series DC/DC converters are UL 60950 recognized and certified in accordance with EN 60950.

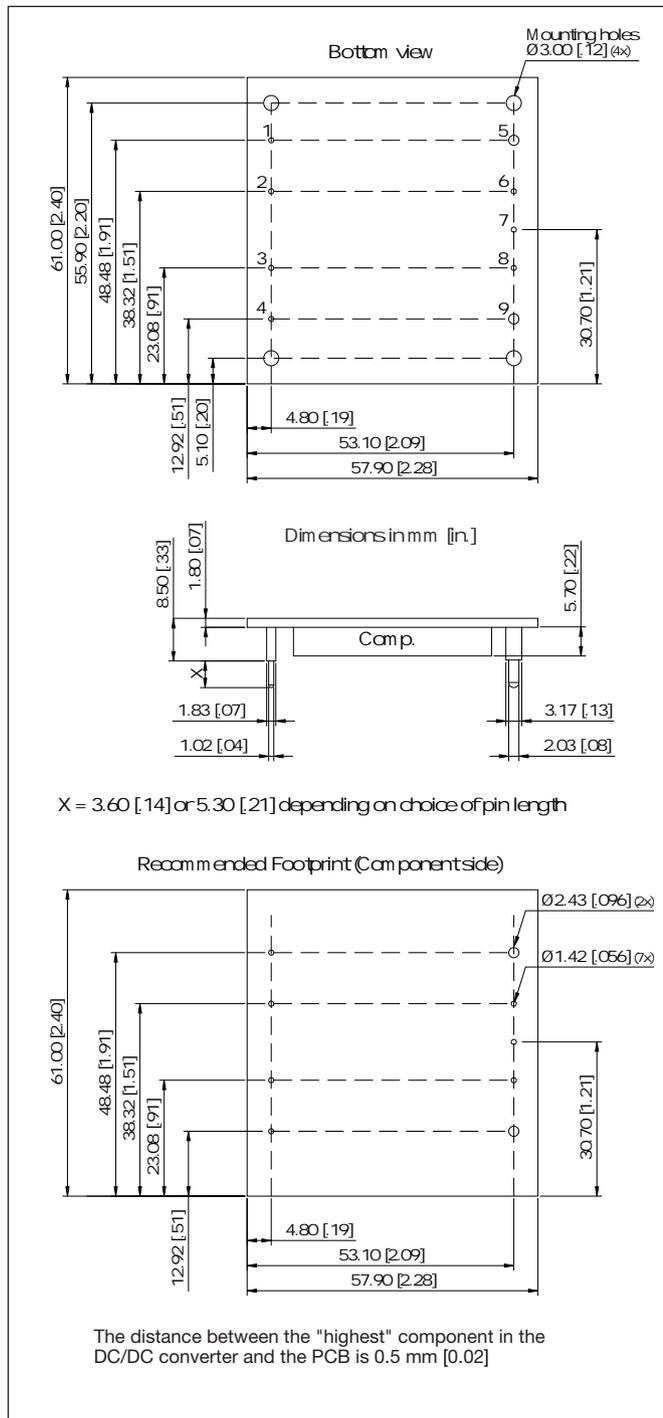
The DC/DC converter should be installed in the end-use equipment, in accordance with the requirements of the ultimate application. The input source must be isolated by minimum Basic insulation from the primary circuit in accordance with IEC/EN/UL 60950. If the input voltage to the DC/DC converter is 75 V dc or less, then the output remains SELV (Safety Extra Low Voltage) under normal and abnormal operating conditions. Single fault testing in the input power supply circuit should be performed with the DC/DC converter connected to demonstrate that the input voltage does not exceed 75 V dc. If the input power source circuit is a DC power system, the source may be treated as a TNV2 circuit and testing has demonstrated compliance with SELV limits and isolation requirements equivalent to Basic insulation in accordance with IEC/EN/UL 60950. It is recommended that a fast blow fuse with a rating of 10A be used at the input of each DC/DC converter. The PKJ series DC/DC converters are approved for a maximum fuse rating of 15A. If a fault occurs in the converter that imposes a short circuit on the input source, this fuse will provide the following functions:

- Isolate the faulty DC/DC converter from the input power source not to affect the operation of other parts of the system.
- Protect the distribution wiring from excessive current and power loss thus preventing hazardous overheating.

The galvanic isolation is verified in an electric strength test. The test voltage (V_{ISO}) between input and output is 1500 Vdc for 60 seconds. Leakage current is less than 1µA at nominal input voltage.

The flammability rating for all construction parts of the DC/DC converter meets UL 94V-0.

Mechanical Data



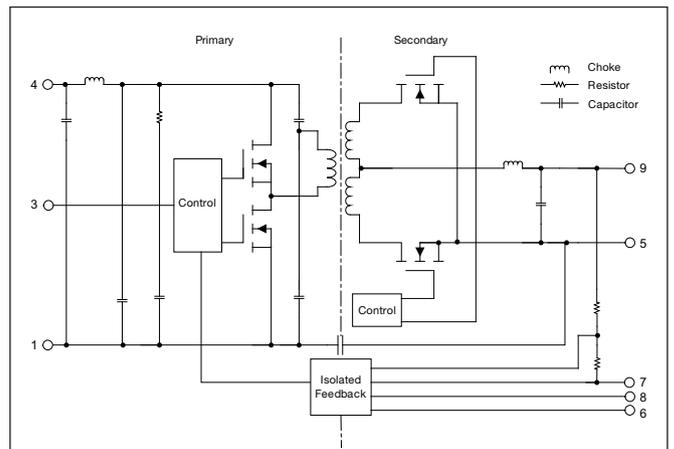
Connections

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| Pin | Designation | Function |
|-----|-------------|-----------------------|
| 1 | - In | Negative Input |
| 2 | | No pin |
| 3 | RC | Remote Control |
| 4 | + In | Positive Input |
| 5 | - Out | Negative Output |
| 6 | - Sen | Negative Remote Sense |
| 7 | V_{adj} | Output voltage adjust |
| 8 | + Sen | Positive Remote Sense |
| 9 | + Out | Positive Output |

For more information about the functions see Operating Information

Fundamental Circuit Diagram



Weight

PKJ 4810E PI 35 g

Pins

Material: Brass Alloy

Plating: 0.1 μm Gold over Nickel

$T_{Pcb} = -30...+90^{\circ}C$, $V_I = 36 ...75V$, sense pins connected to output pins unless otherwise specified.

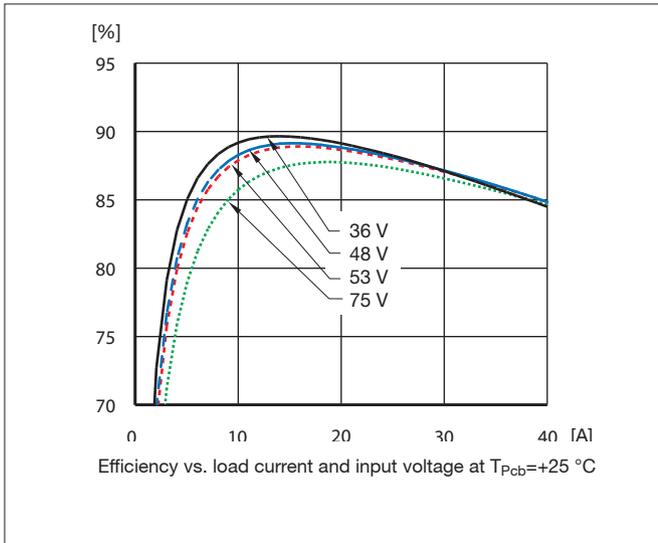
| Characteristics | | Conditions | Output | | | Unit |
|-----------------|---|--|--------|-----------|-------|-------------------|
| | | | min | typ | max | |
| V_{O_i} | Output voltage initial setting and accuracy | $T_{Pcb} = +25^{\circ}C$, $V_I = 53 V$, $I_O = I_{Omax}$ | 1.485 | 1.50 | 1.515 | V |
| | Output adjust range | $I_O = I_{Omax}$ | 1.35 | | 1.65 | V |
| V_O | Output voltage tolerance band | $I_O = 0.1...1 \times I_{Omax}$ | 1.465 | | 1.535 | V |
| | Idling voltage | $I_O = 0$ | 1.465 | | 1.535 | V |
| | Line regulation | $I_O = I_{Omax}$ | | | 5 | mV |
| | Load regulation | $V_I = 53 V$, $I_O = 0.01...1 \times I_{Omax}$ | | | 5 | mV |
| V_{tr} | Load transient voltage deviation | $I_O = 0.1...1 \times I_{Omax}$, $V_I = 53 V$ Load step = $0.5 \times I_{Omax}$ di/dt = $1A/\mu s$ | | ± 150 | | mV |
| t_{tr} | Load transient recovery time | $I_O = 0.1...1 \times I_{Omax}$, $V_I = 53$ loadstep = $0.5 \times I_{Omax}$ | | 100 | | μs |
| t_r | Ramp-up time | $I_O = 0.1...0.9 \times V_O$ | | 15 | 30 | ms |
| t_s | Start-up time | From V_I connected to $V_O = 0.9 \times V_{O_i}$ | | 20 | 40 | ms |
| I_O | Output current | | 0 | | 40 | A |
| P_{Omax} | Max output power | At $V_O = V_{Onom}$ | 60 | | | W |
| I_{lim} | Current limit threshold | $T_{Pcb} < T_{Pcbmax}$ | | 46 | | A |
| I_{sc} | Short circuit current | $T_{Pcb} = 25^{\circ}C$ | | 50 | | A |
| V_{Oac} | Output ripple & noise | See ripple and noise, $I_O = I_{Omax}$ | | 150 | 200 | mV _{p-p} |
| SVR | Supply voltage rejection (ac) | $f = 100$ Hz sinewave, 1 V _{p-p} , $V_I = 53 V$ | | 65 | | dB |
| OVP | Over voltage protection | $V_I = 53 V$ | 1.7 | | 2.2 | V |

Miscellaneous

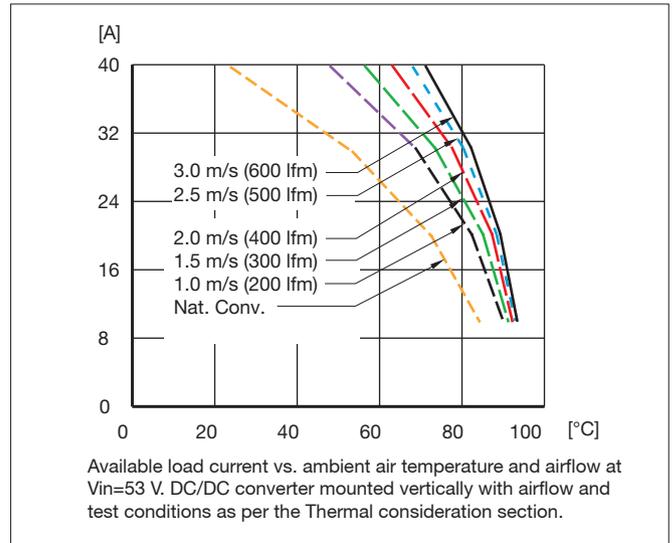
| Characteristics | | Conditions | min | typ | max | Unit |
|-----------------|------------------------|---|-----|------|-----|------|
| η | Efficiency - 50% load | $T_{Pcb} = +25^{\circ}C$, $V_I = 48 V$, $I_O = 0.5 \times I_{Omax}$ | | 88.5 | | % |
| η | Efficiency - 100% load | $T_{Pcb} = +25^{\circ}C$, $V_I = 48 V$, $I_O = I_{Omax}$ | | 85 | | % |
| η | Efficiency - 50% load | $T_{Pcb} = +25^{\circ}C$, $V_I = 53 V$, $I_O = 0.5 \times I_{Omax}$ | | 88.5 | | % |
| η | Efficiency - 100% load | $T_{Pcb} = +25^{\circ}C$, $V_I = 53 V$, $I_O = I_{Omax}$ | 83 | 85 | | % |
| P_d | Power Dissipation | $T_{Pcb} = +25^{\circ}C$, $V_I = 53 V$, $I_O = I_{Omax}$ | | 11 | | W |
| f_s | Switching frequency | $I_O = 0 ... 1.0 \times I_{Omax}$ | | 140 | | kHz |
| I_{Imax} | Maximum input current | $1.1 \times V_{O_i} \times I_{Omax} / \eta / V_{Imin}$ | | 2.2 | | A |

PKJ 4618HE PI Typical Characteristics

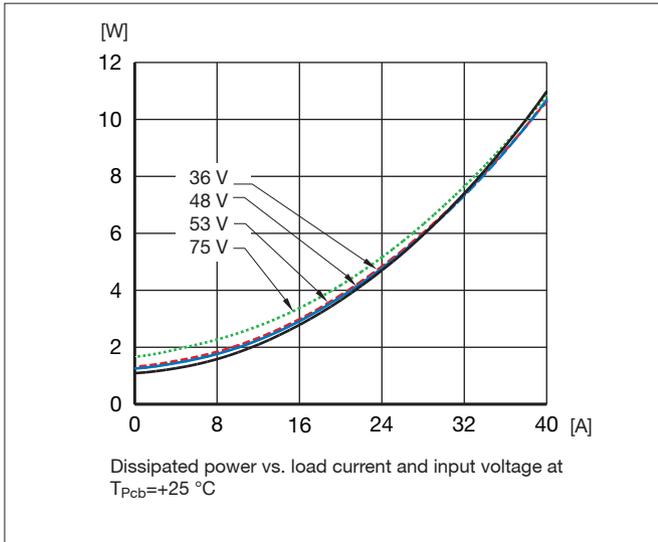
Efficiency



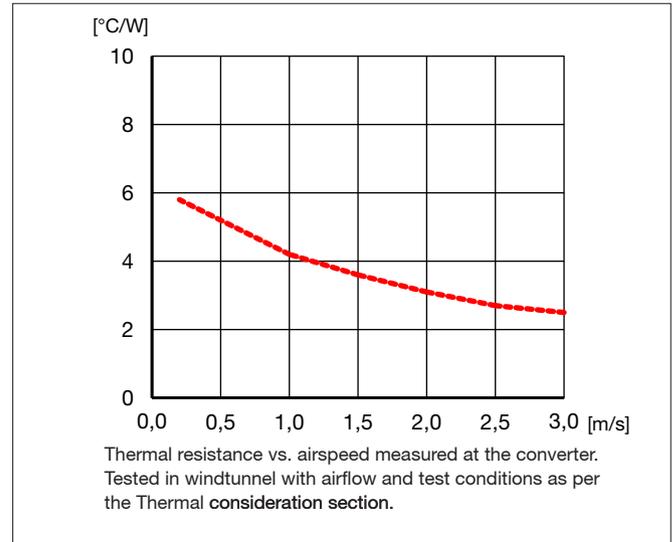
Output Current Derating



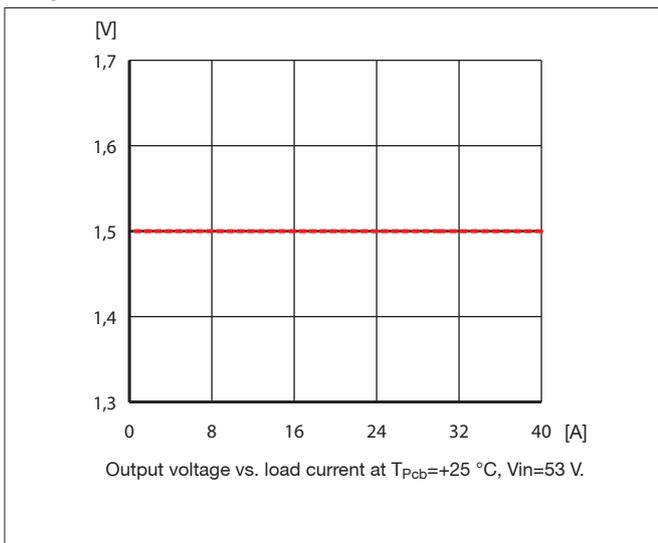
Power Dissipation



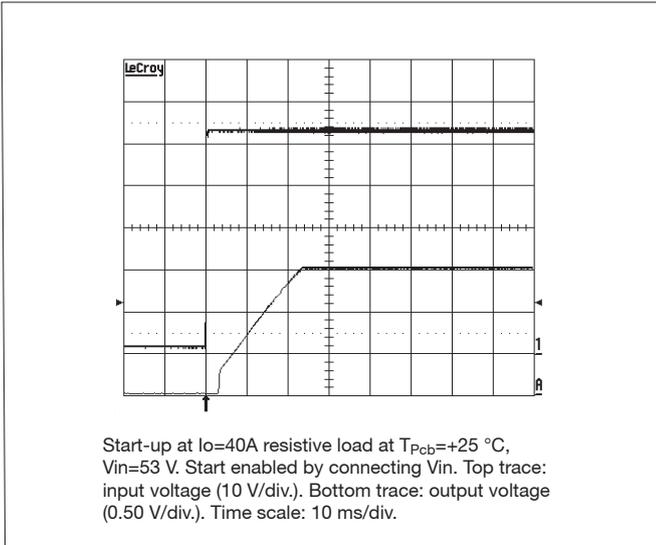
Thermal Resistance



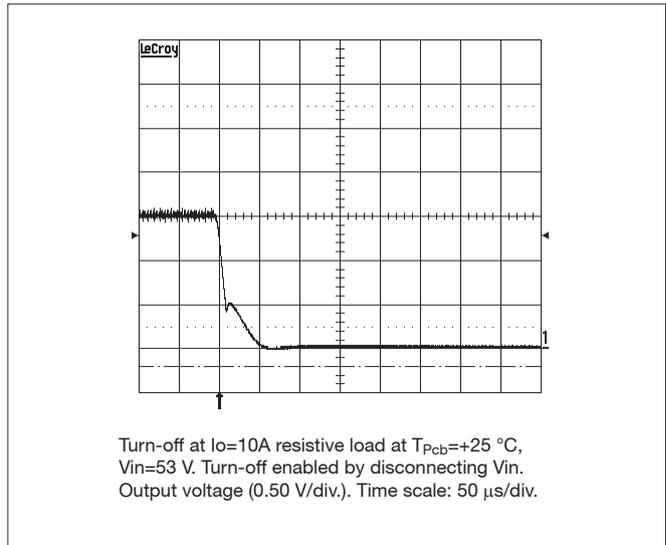
Output Characteristic



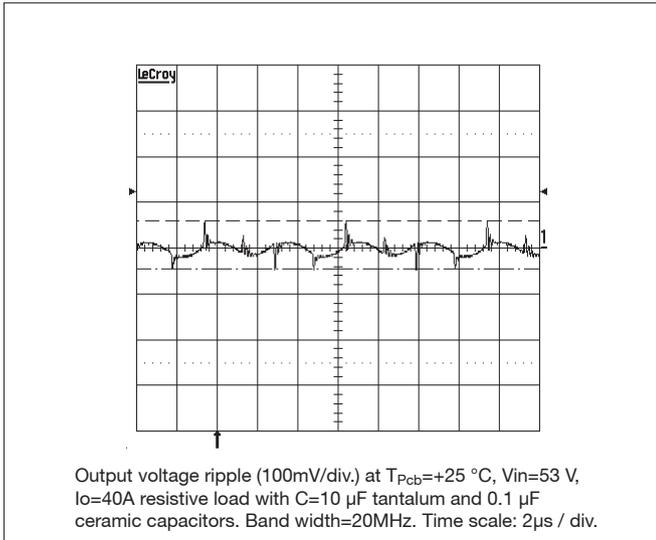
Start-Up



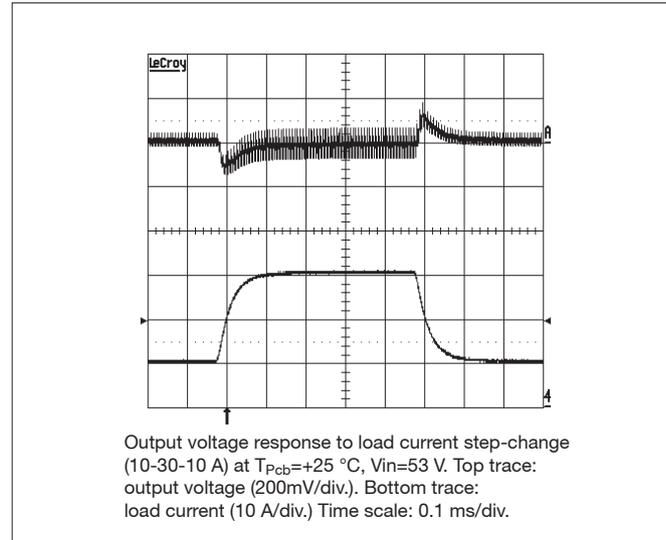
Turn-Off



Output Ripple



Transient



Output Voltage Adjust

The resistor value for an adjusted output voltage is calculated by using the following equations:

Output Voltage Adjust Upwards, Increase:

$$R_{adj} = [1.5(100+\Delta\%) / 1.225\Delta\% - (100+2\Delta\%) / \Delta\%] \text{ kOhm}$$

Output Voltage Adjust Downwards, Decrease:

$$R_{adj} = [(100 / \Delta\% - 2)] \text{ kOhm}$$

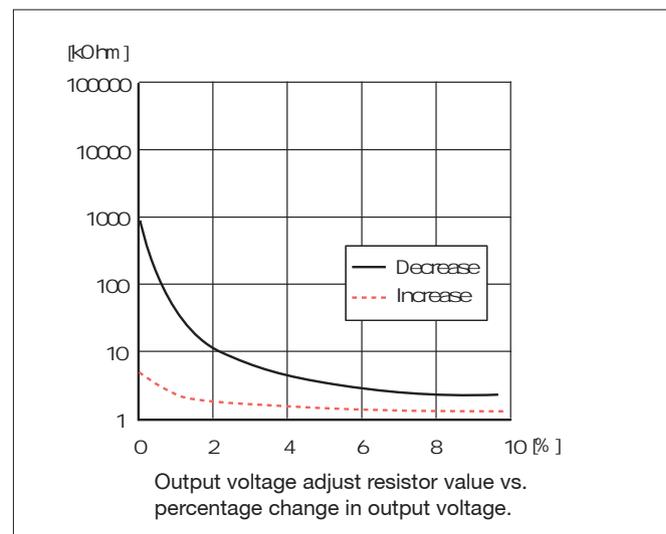
Eg Increase 4% => $V_{out} = 1.56\text{ V}_{dc}$

$$1.5 (100+4) / 1.225 \times 4 - 100 + 2 \times 4 / 4 = 4.84 \text{ kOhm}$$

Eg Decrease 2% => $V_{out} = 1.47\text{ V}_{dc}$

$$100 / 2 - 2 = 48.0 \text{ kOhm}$$

Output Voltage Adjust



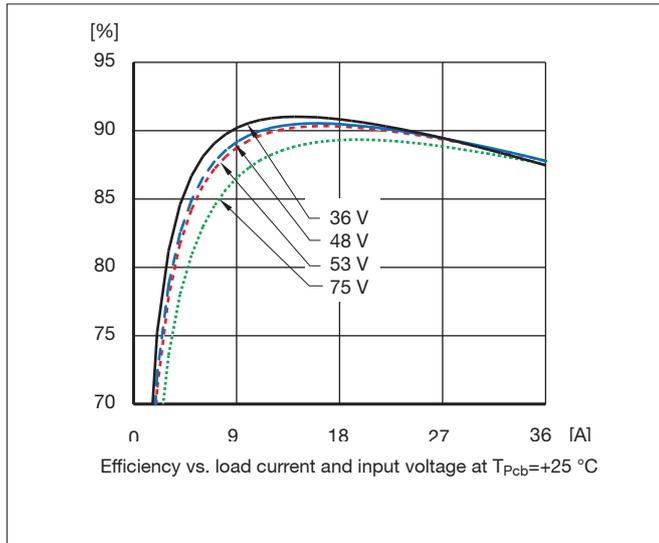
$T_{Pcb} = -30...+90^{\circ}C$, $V_I = 36 ...75V$, sense pins connected to output pins unless otherwise specified.

| Characteristics | | Conditions | Output | | | Unit |
|-----------------|---|--|--------|-----------|-------|-------------------|
| | | | min | typ | max | |
| V_{O_i} | Output voltage initial setting and accuracy | $T_{Pcb} = +25^{\circ}C$, $V_I = 53 V$, $I_O = I_{Omax}$ | 1.782 | 1.80 | 1.818 | V |
| | Output adjust range | $I_O = I_{Omax}$ | 1.62 | | 1.98 | V |
| V_O | Output voltage tolerance band | $I_O = 0.1...1 \times I_{Omax}$ | 1.758 | | 1.842 | V |
| | Idling voltage | $I_O = 0$ | 1.758 | | 1.842 | V |
| | Line regulation | $I_O = I_{Omax}$ | | | 5 | mV |
| | Load regulation | $V_I = 53 V$, $I_O = 0.01...1 \times I_{Omax}$ | | | 5 | mV |
| V_{tr} | Load transient voltage deviation | $I_O = 0.1...1 \times I_{Omax}$, $V_I = 53 V$ Load step = $0.5 \times I_{Omax}$ di/dt = $1A/\mu s$ | | ± 150 | | mV |
| t_{tr} | Load transient recovery time | $I_O = 0.1...1 \times I_{Omax}$, $V_I = 53$ loadstep = $0.5 \times I_{Omax}$ | | 100 | | μs |
| t_r | Ramp-up time | $I_O = 0.1...0.9 \times V_O$ | | 15 | 30 | ms |
| t_s | Start-up time | From V_I connected to $V_O = 0.9 \times V_{O_i}$ | | 20 | 40 | ms |
| I_O | Output current | | 0 | | 36 | A |
| P_{Omax} | Max output power | At $V_O = V_{Onom}$ | 65 | | | W |
| I_{lim} | Current limit threshold | $T_{Pcb} < T_{Pcbmax}$ | | 43 | | A |
| I_{sc} | Short circuit current | $T_{Pcb} = 25^{\circ}C$ | | 47 | | A |
| V_{Oac} | Output ripple & noise | See ripple and noise, $I_O = I_{Omax}$ | | 150 | 200 | mV _{p-p} |
| SVR | Supply voltage rejection (ac) | f = 100 Hz sinewave , 1 V _{p-p} , $V_I = 53 V$ | | 65 | | dB |
| OVP | Over voltage protection | $V_I = 53 V$ | 2.0 | | 3.0 | V |

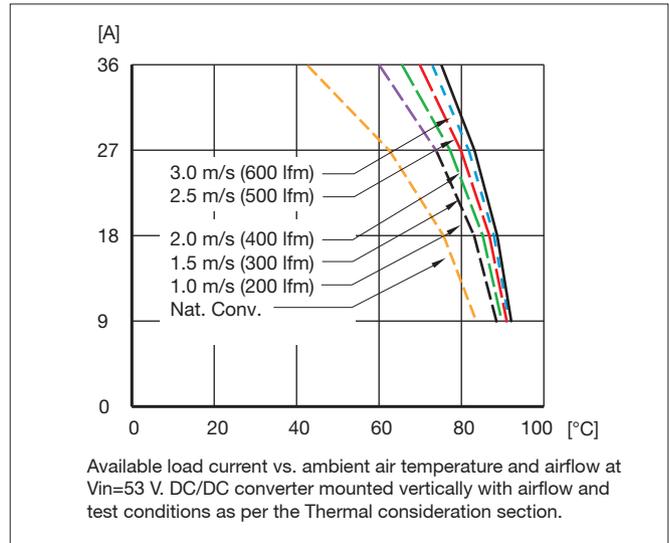
Miscellaneous

| Characteristics | | Conditions | min | typ | max | Unit |
|-----------------|------------------------|---|------|------|-----|------|
| η | Efficiency - 50% load | $T_{Pcb} = +25^{\circ}C$, $V_I = 48 V$, $I_O = 0.5 \times I_{Omax}$ | | 90.5 | | % |
| η | Efficiency - 100% load | $T_{Pcb} = +25^{\circ}C$, $V_I = 48 V$, $I_O = I_{Omax}$ | | 87.5 | | % |
| η | Efficiency - 50% load | $T_{Pcb} = +25^{\circ}C$, $V_I = 53 V$, $I_O = 0.5 \times I_{Omax}$ | | 90 | | % |
| η | Efficiency - 100% load | $T_{Pcb} = +25^{\circ}C$, $V_I = 53 V$, $I_O = I_{Omax}$ | 85.5 | 87.5 | | % |
| P_d | Power Dissipation | $T_{Pcb} = +25^{\circ}C$, $V_I = 53 V$, $I_O = I_{Omax}$ | | 9 | | W |
| f_s | Switching frequency | $I_O = 0 ... 1.0 \times I_{Omax}$ | | 140 | | kHz |
| $I_{I_{max}}$ | Maximum input current | $1.1 \times V_{O_i} \times I_{Omax} / \eta / V_{Imin}$ | | 2.3 | | A |

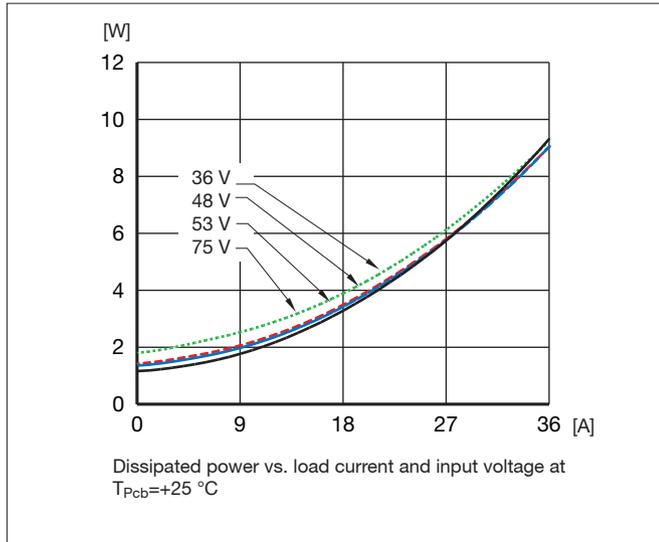
Efficiency



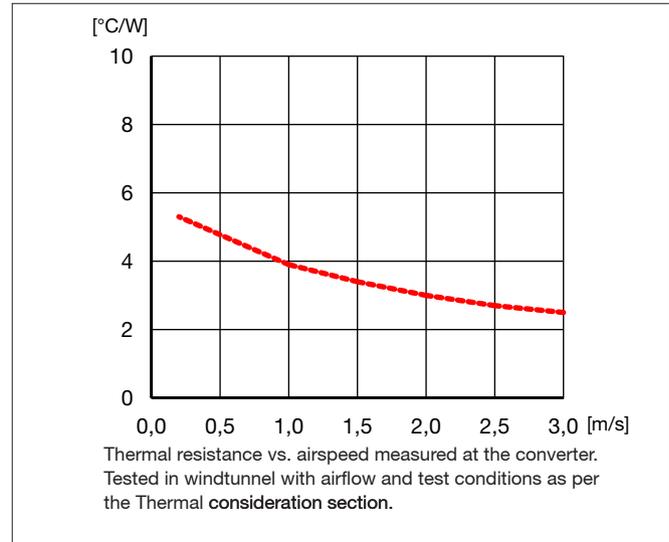
Output Current Derating



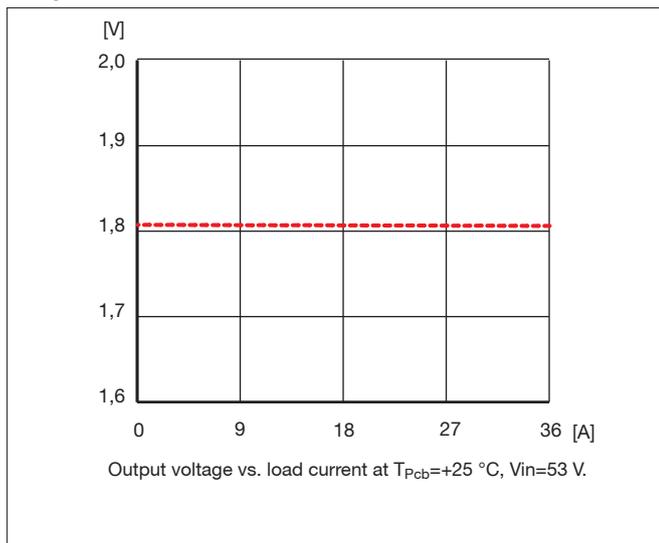
Power Dissipation



Thermal Resistance

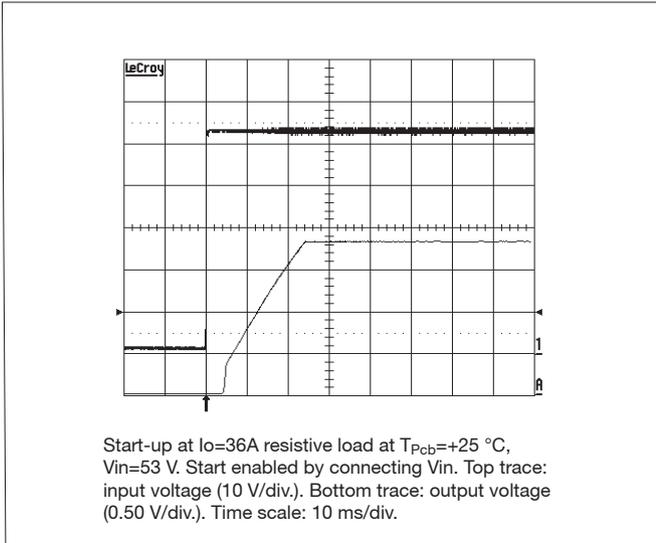


Output Characteristic

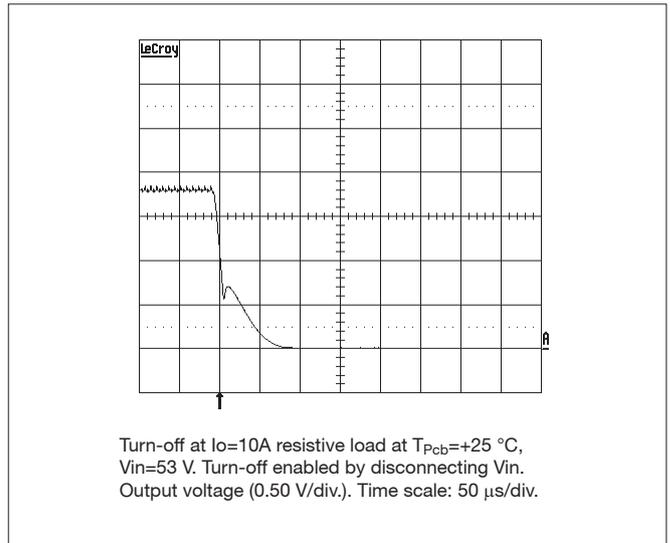


PKJ 4618GE PI Typical Characteristics

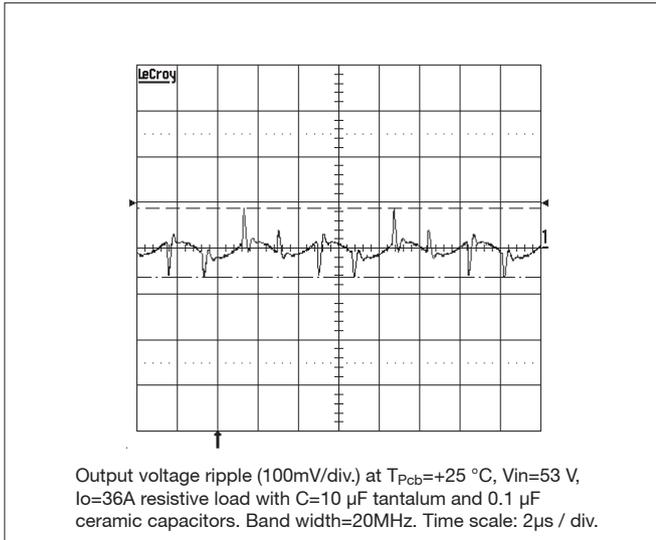
Start-Up



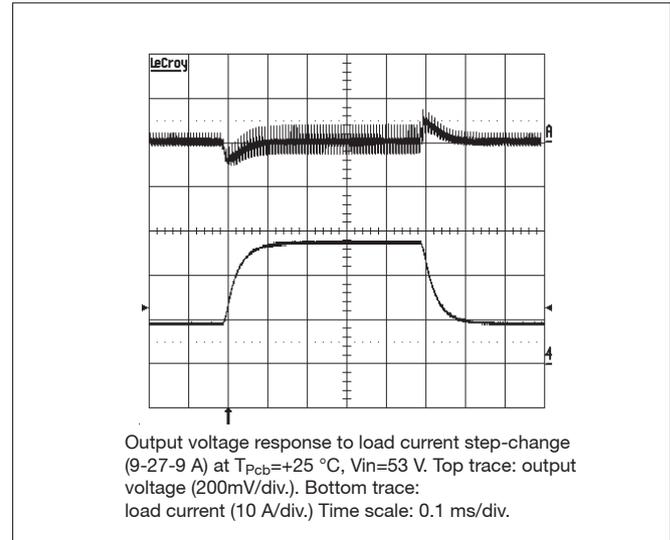
Turn-Off



Output Ripple



Transient



Output Voltage Adjust

The resistor value for an adjusted output voltage is calculated by using the following equations:

Output Voltage Adjust Upwards, Increase:

$$R_{adj} = [1.8(100+\Delta\%)/1.225\Delta\% - (100+2\Delta\%)/\Delta\%] \text{ k}\Omega\text{m}$$

Output Voltage Adjust Downwards, Decrease:

$$R_{adj} = [(100/\Delta\% - 2)] \text{ k}\Omega\text{m}$$

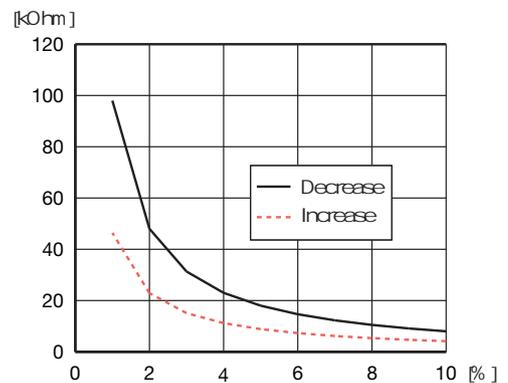
Eg Increase 4% $\Rightarrow V_{out} = 1.87 V_{dc}$

$$1.8 (100+4)/1.225 \times 4 - 100 + 2 \times 4/4 = 11.2 \text{ k}\Omega\text{m}$$

Eg Decrease 2% $\Rightarrow V_{out} = 1.76 V_{dc}$

$$100/2 - 2 = 48.0 \text{ k}\Omega\text{m}$$

Output Voltage Adjust



Output voltage adjust resistor value vs. percentage change in output voltage.

$T_{Pcb} = -30...+90^{\circ}C$, $V_I = 36 ...75V$, sense pins connected to output pins unless otherwise specified.

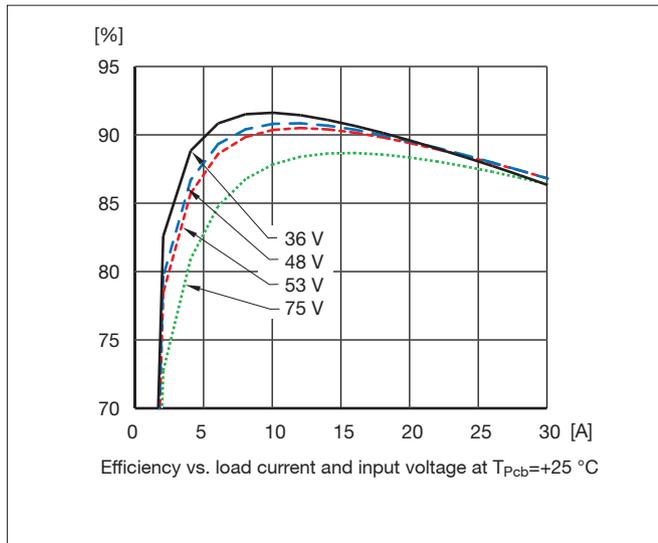
| Characteristics | | Conditions | Output | | | Unit |
|-----------------|---|--|--------|-----------|-------|-------------------|
| | | | min | typ | max | |
| V_{Oi} | Output voltage initial setting and accuracy | $T_{Pcb} = +25^{\circ}C$, $V_I = 53 V$, $I_O = I_{Omax}$ | 2.475 | 2.50 | 2.525 | V |
| | Output adjust range | $I_O = I_{Omax}$ | 2.00 | | 2.75 | V |
| V_O | Output voltage tolerance band | $I_O = 0.1...1 \times I_{Omax}$ | 2.44 | | 2.56 | V |
| | Idling voltage | $I_O = 0$ | 2.44 | | 2.56 | V |
| | Line regulation | $I_O = I_{Omax}$ | | | 5 | mV |
| | Load regulation | $V_I = 53 V$, $I_O = 0.01...1 \times I_{Omax}$ | | | 5 | mV |
| V_{tr} | Load transient voltage deviation | $I_O = 0.1...1 \times I_{Omax}$, $V_I = 53 V$ Load step = $0.5 \times I_{Omax}$ di/dt = $1A/\mu s$ | | ± 200 | | mV |
| t_{tr} | Load transient recovery time | $I_O = 0.1...1 \times I_{Omax}$, $V_I = 53$ loadstep = $0.5 \times I_{Omax}$ | | 100 | | μs |
| t_r | Ramp-up time | $I_O = 0.1...0.9 \times V_O$ | | 15 | 30 | ms |
| t_s | Start-up time | From V_I connected to $V_O = 0.9 \times V_{OI}$ | | 20 | 40 | ms |
| I_O | Output current | | 0 | | 30 | A |
| P_{Omax} | Max output power | At $V_O = V_{Onom}$ | 75 | | | W |
| I_{lim} | Current limit threshold | $T_{Pcb} < T_{Pcbmax}$ | | 32 | | A |
| I_{sc} | Short circuit current | $T_{Pcb} = 25^{\circ}C$ | | 40 | | A |
| V_{Oac} | Output ripple & noise | See ripple and noise, $I_O = I_{Omax}$ | | 150 | 200 | mV _{p-p} |
| SVR | Supply voltage rejection (ac) | $f = 100$ Hz sinewave , $1 V_{p-p}$, $V_I = 53 V$ | | 70 | | dB |
| OVP | Over voltage protection | $V_I = 53 V$ | 3.0 | | 4.0 | V |

Miscellaneous

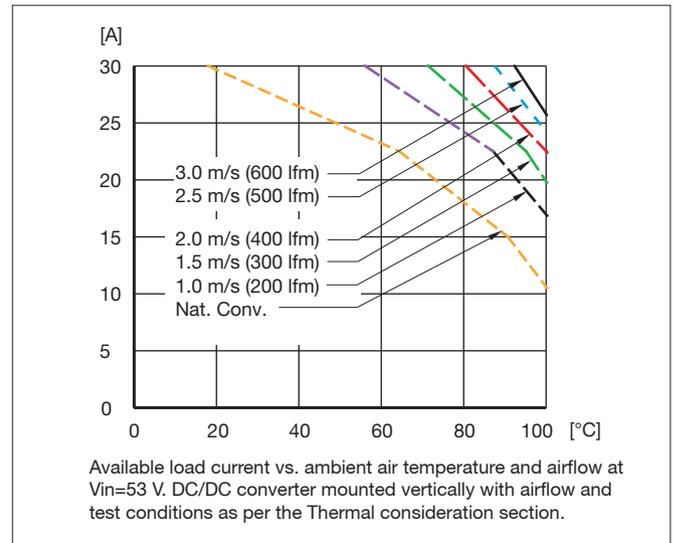
| Characteristics | | Conditions | min | typ | max | Unit |
|-----------------|------------------------|---|------|------|-----|------|
| η | Efficiency - 50% load | $T_{Pcb} = +25^{\circ}C$, $V_I = 48 V$, $I_O = 0.5 \times I_{Omax}$ | | 90.5 | | % |
| η | Efficiency - 100% load | $T_{Pcb} = +25^{\circ}C$, $V_I = 48 V$, $I_O = I_{Omax}$ | | 87 | | % |
| η | Efficiency - 50% load | $T_{Pcb} = +25^{\circ}C$, $V_I = 53 V$, $I_O = 0.5 \times I_{Omax}$ | | 90 | | % |
| η | Efficiency - 100% load | $T_{Pcb} = +25^{\circ}C$, $V_I = 53 V$, $I_O = I_{Omax}$ | 85.5 | 86.5 | | % |
| P_d | Power Dissipation | $T_{Pcb} = +25^{\circ}C$, $V_I = 53 V$, $I_O = I_{Omax}$ | | 12 | | W |
| f_s | Switching frequency | $I_O = 0 ... 1.0 \times I_{Omax}$ | | 140 | | kHz |
| I_{Imax} | Maximum input current | $1.1 \times V_{OI} \times I_{Omax} / \eta / V_{Imin}$ | | 2.6 | | A |

PKJ 4719E PI Typical Characteristics

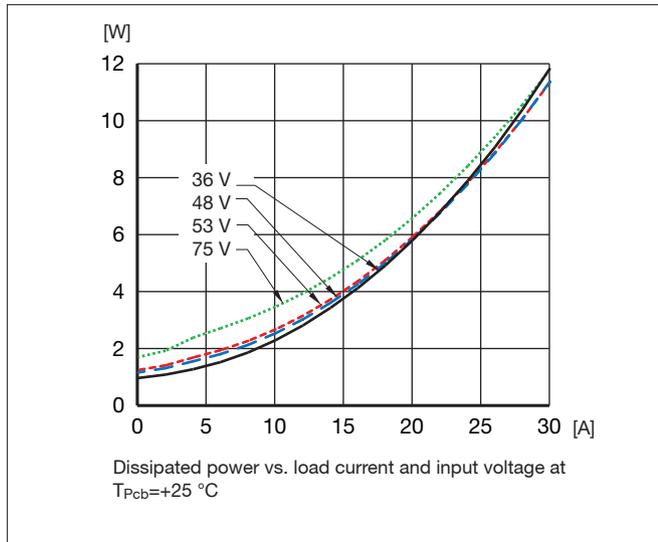
Efficiency



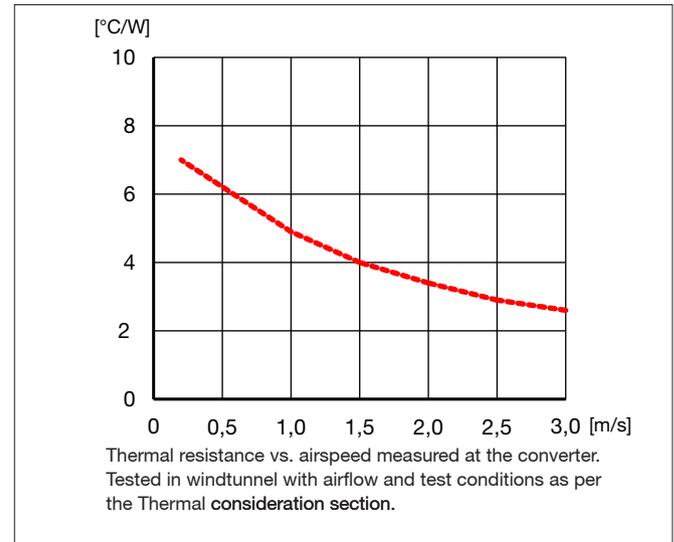
Output Current Derating



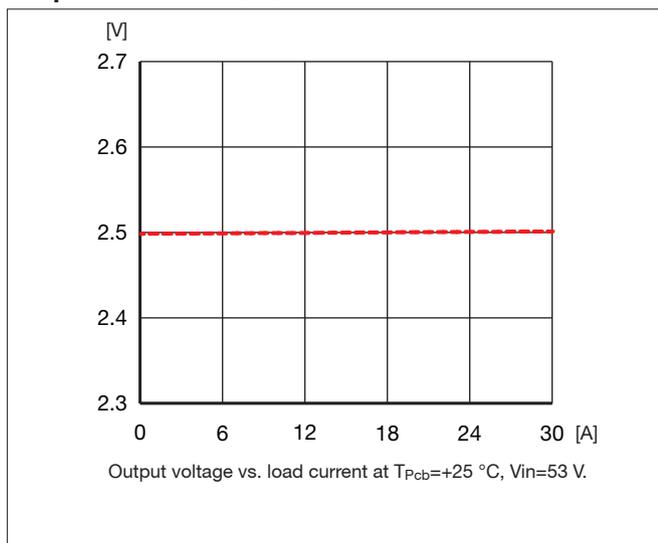
Power Dissipation



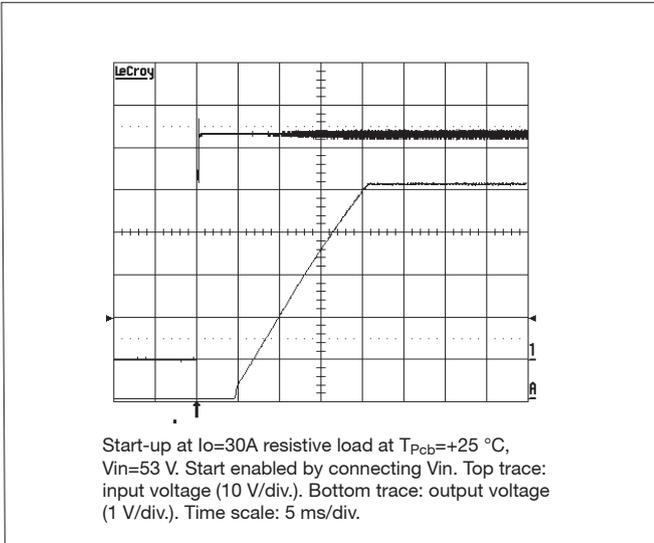
Thermal Resistance



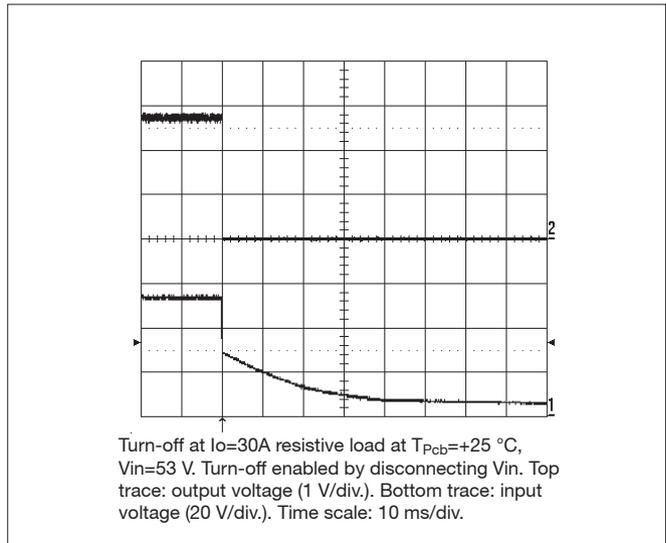
Output Characteristic



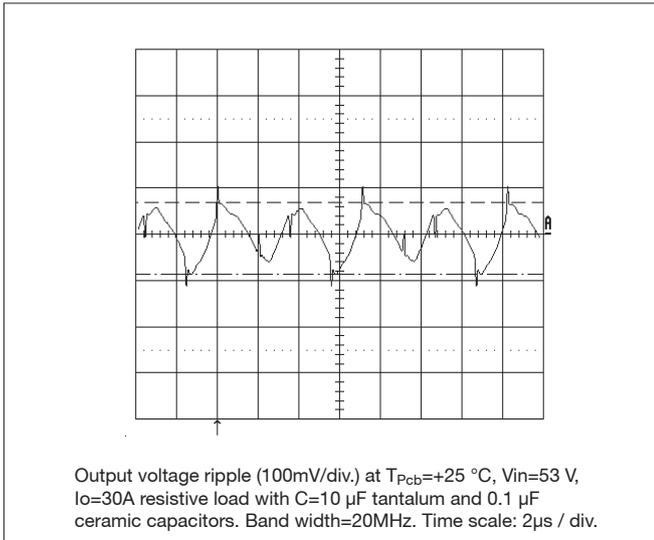
Start-Up



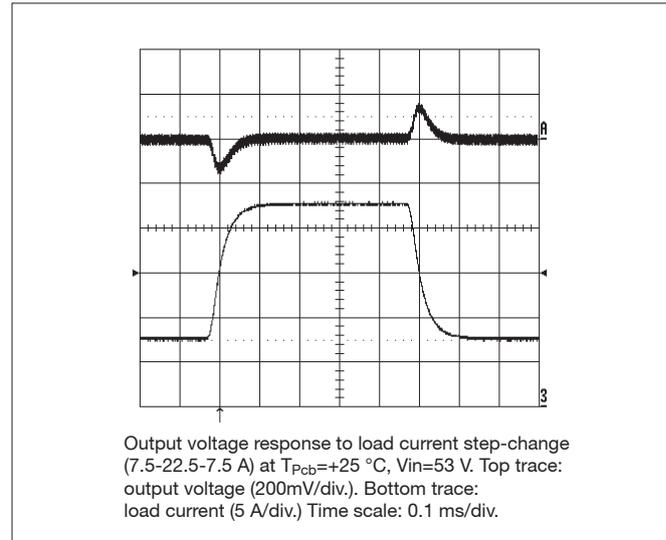
Turn-Off



Output Ripple



Transient



Output Voltage Adjust

The resistor value for an adjusted output voltage is calculated by using the following equations:

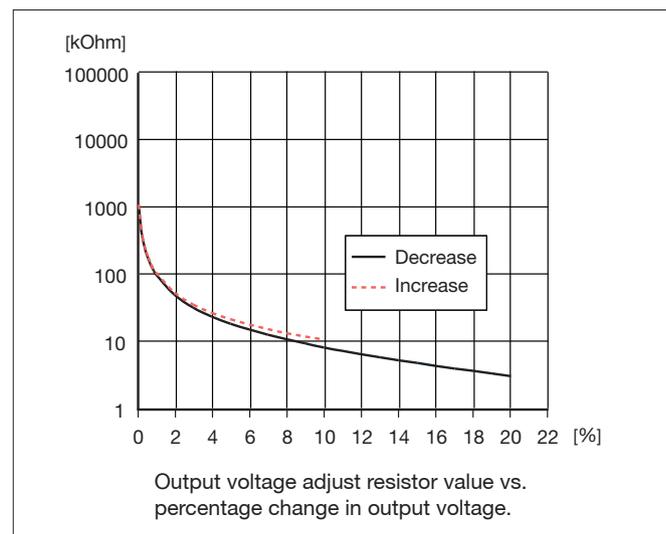
Output Voltage Adjust Upwards, Increase:
 $R_{adj} = [2.5(100+\Delta\%)/1.225\Delta\% - (100+2\Delta\%)/\Delta\%]$ kOhm

Output Voltage Adjust Downwards, Decrease:
 $R_{adj} = [(100/\Delta\% - 2)]$ kOhm

Eg Increase 4% $\Rightarrow V_{out} = 2.600\text{ V}_{dc}$
 $2.5(100+4)/1.225 \times 4 - 100 + 2 \times 4 / 4 = 26.06\text{ kOhm}$

Eg Decrease 2% $\Rightarrow V_{out} = 2.450\text{ V}_{dc}$
 $100/2 - 2 = 48.0\text{ kOhm}$

Output Voltage Adjust



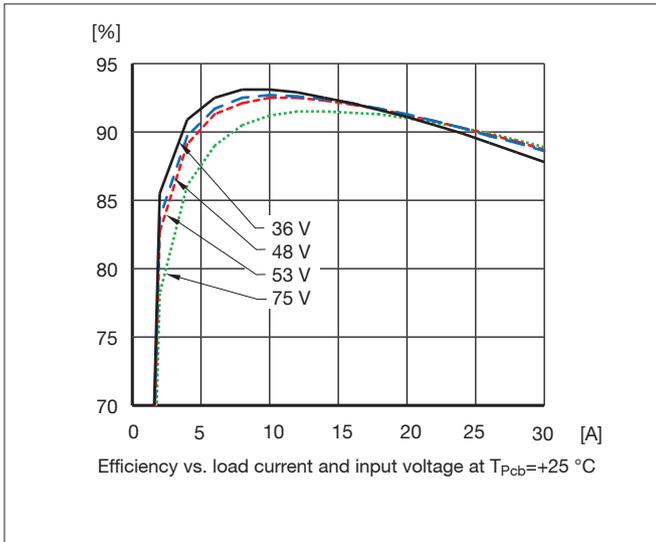
$T_{Pcb} = -30...+90^{\circ}C$, $V_I = 36 ...75V$, sense pins connected to output pins unless otherwise specified.

| Characteristics | | Conditions | Output | | | Unit |
|-----------------|---|--|--------|-----------|------|-------------------|
| | | | min | typ | max | |
| V_{OI} | Output voltage initial setting and accuracy | $T_{Pcb} = +25^{\circ}C$, $V_I = 53 V$, $I_O = I_{Omax}$ | 3.26 | 3.30 | 3.34 | V |
| | Output adjust range | $I_O = I_{Omax}$ | 2.64 | | 3.63 | V |
| V_O | Output voltage tolerance band | $I_O = 0.1...1 \times I_{Omax}$ | 3.24 | | 3.36 | V |
| | Idling voltage | $I_O = 0$ | 3.24 | | 3.36 | V |
| | Line regulation | $I_O = I_{Omax}$ | | | 5 | mV |
| | Load regulation | $V_I = 53 V$, $I_O = 0.01...1 \times I_{Omax}$ | | | 5 | mV |
| V_{tr} | Load transient voltage deviation | $I_O = 0.1...1 \times I_{Omax}$, $V_I = 53 V$ Load step = $0.5 \times I_{Omax}$ $di/dt = 1A/\mu s$ | | ± 300 | | mV |
| t_{tr} | Load transient recovery time | $I_O = 0.1...1 \times I_{Omax}$, $V_I = 53 V$ loadstep = $0.5 \times I_{Omax}$ | | 100 | | μs |
| t_r | Ramp-up time | $I_O = 0.1...0.9 \times V_O$ | | 15 | 30 | ms |
| t_s | Start-up time | From V_I connected to $V_O = 0.9 \times V_{OI}$ | | 20 | 40 | ms |
| I_O | Output current | | 0 | | 25 | A |
| P_{Omax} | Max output power | At $V_O = V_{Onom}$ | 82.5 | | | W |
| I_{lim} | Current limit threshold | $T_{Pcb} < T_{Pcbmax}$ | | 29 | | A |
| I_{sc} | Short circuit current | $T_{Pcb} = 25^{\circ}C$ | | 33 | | A |
| V_{Oac} | Output ripple & noise | See ripple and noise, $I_O = I_{Omax}$ | | 120 | 150 | mV _{p-p} |
| SVR | Supply voltage rejection (ac) | $f = 100 \text{ Hz}$ sinewave, 1 Vp-p , $V_I = 53 V$ | | 80 | | dB |
| OVP | Over voltage protection | $V_I = 53 V$ | 3.9 | 4.4 | 5.0 | V |

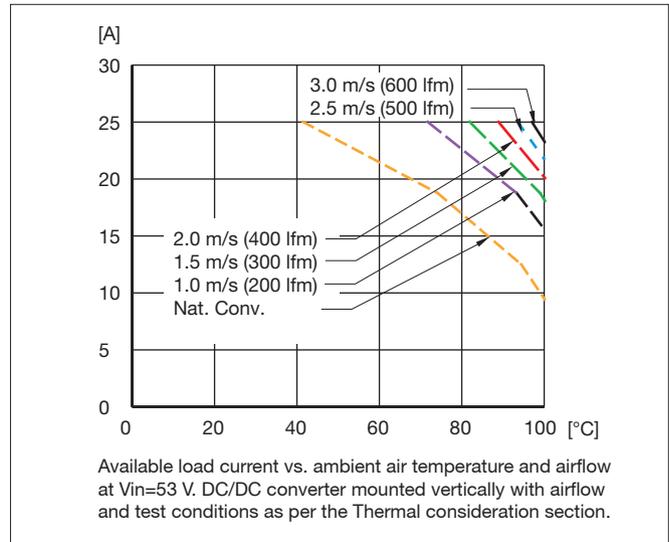
Miscellaneous

| Characteristics | | Conditions | min | typ | max | Unit |
|-----------------|------------------------|---|-----|-----|-----|------|
| η | Efficiency - 50% load | $T_{Pcb} = +25^{\circ}C$, $V_I = 48 V$, $I_O = 0.5 \times I_{Omax}$ | | TBD | | % |
| η | Efficiency - 100% load | $T_{Pcb} = +25^{\circ}C$, $V_I = 48 V$, $I_O = I_{Omax}$ | | TBD | | % |
| η | Efficiency - 50% load | $T_{Pcb} = +25^{\circ}C$, $V_I = 53 V$, $I_O = 0.5 \times I_{Omax}$ | | 93 | | % |
| η | Efficiency - 100% load | $T_{Pcb} = +25^{\circ}C$, $V_I = 53 V$, $I_O = I_{Omax}$ | 87 | 89 | | % |
| P_d | Power Dissipation | $T_{Pcb} = +25^{\circ}C$, $V_I = 53 V$, $I_O = I_{Omax}$ | | 10 | | W |
| f_s | Switching frequency | $I_O = 0 ... 1.0 \times I_{Omax}$ | | 140 | | kHz |
| I_{Imax} | Maximum input current | $1.1 \times V_{OI} \times I_{Omax} / \eta / V_{Imin}$ | | 2.8 | | A |

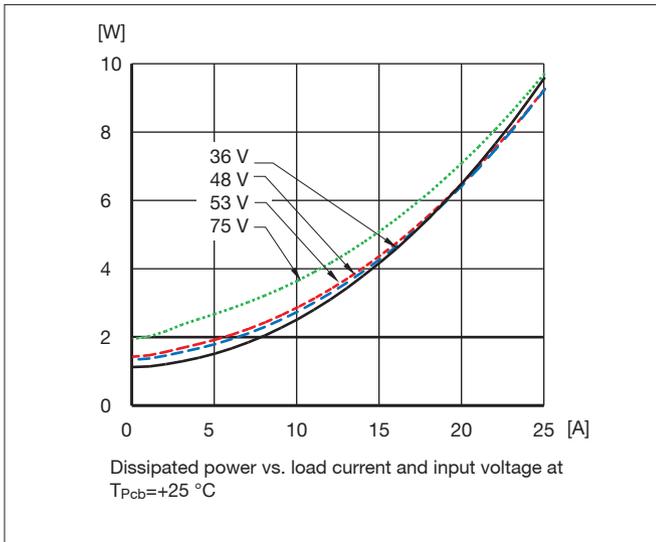
Efficiency



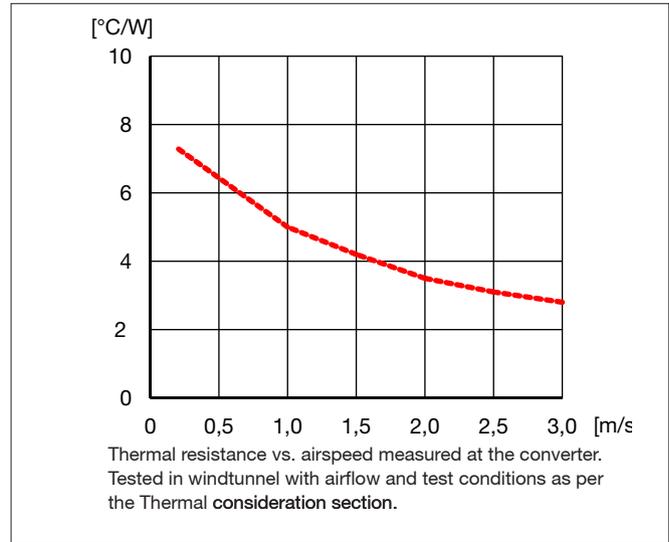
Output Current Derating



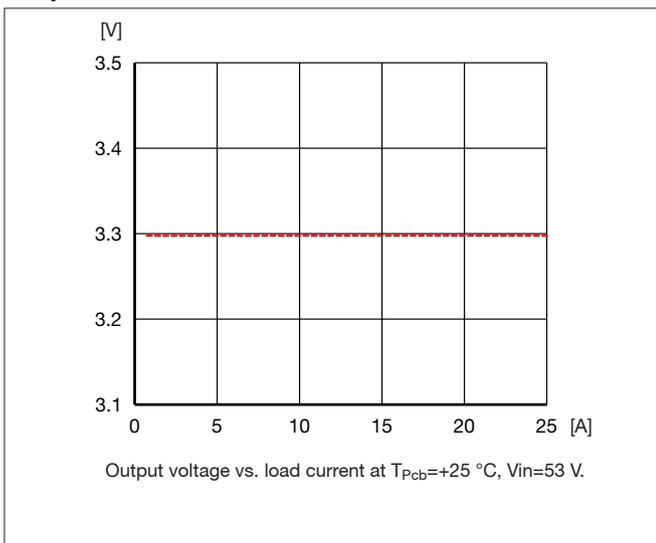
Power Dissipation



Thermal Resistance

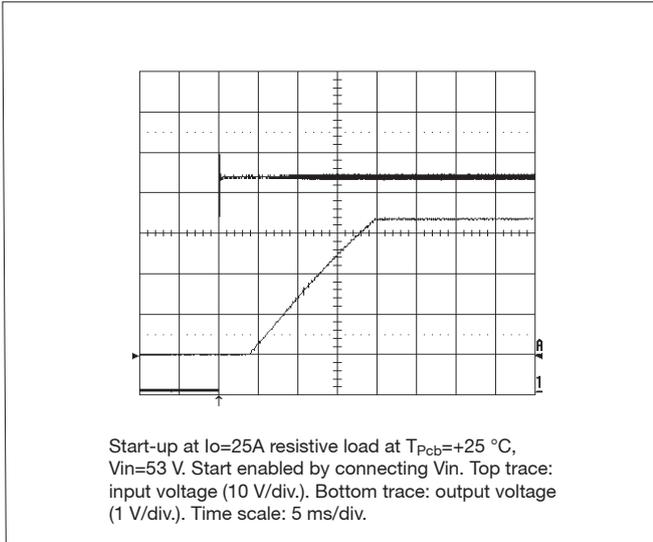


Output Characteristic

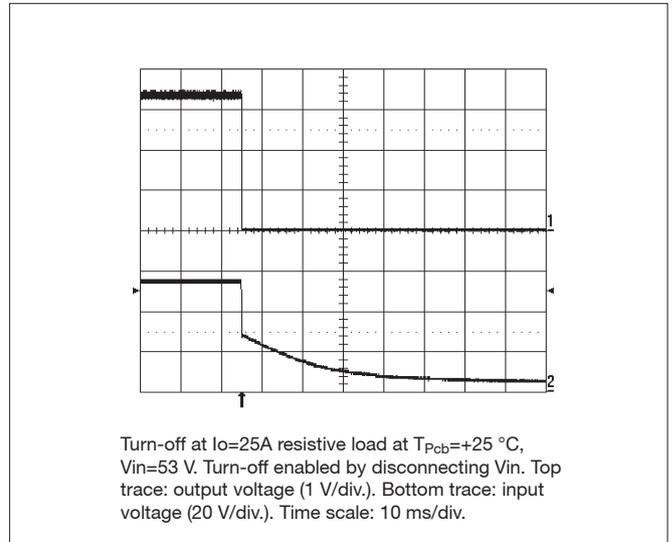


PKJ 4810E PI Typical Characteristics

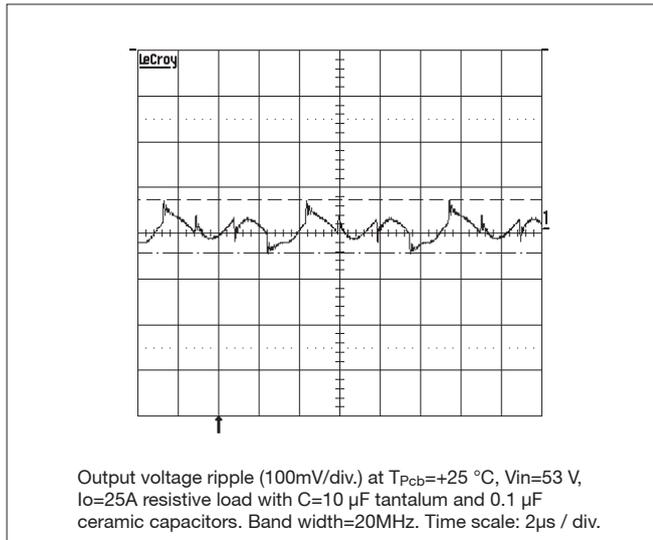
Start-Up



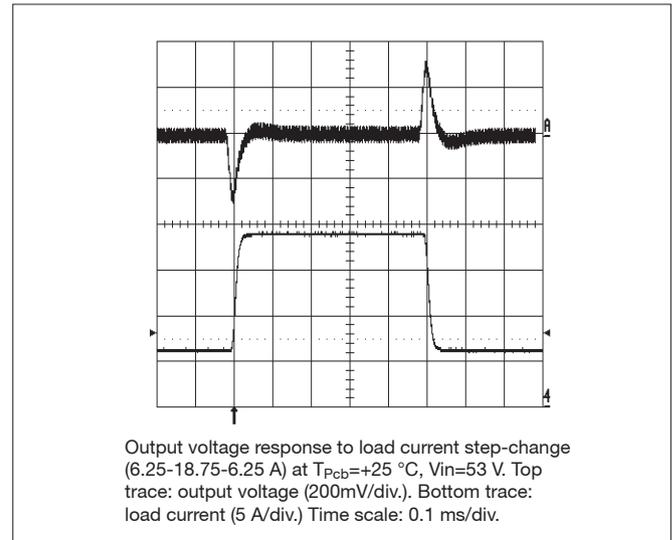
Turn-Off



Output Ripple



Transient



Output Voltage Adjust

The resistor value for an adjusted output voltage is calculated by using the following equations:

Output Voltage Adjust Upwards, Increase:

$$R_{adj} = [3.3(100+\Delta\%) / 1.225\Delta\% - (100+2\Delta\%) / \Delta\%] \text{ kOhm}$$

Output Voltage Adjust Downwards, Decrease:

$$R_{adj} = [(100 / \Delta\% - 2)] \text{ kOhm}$$

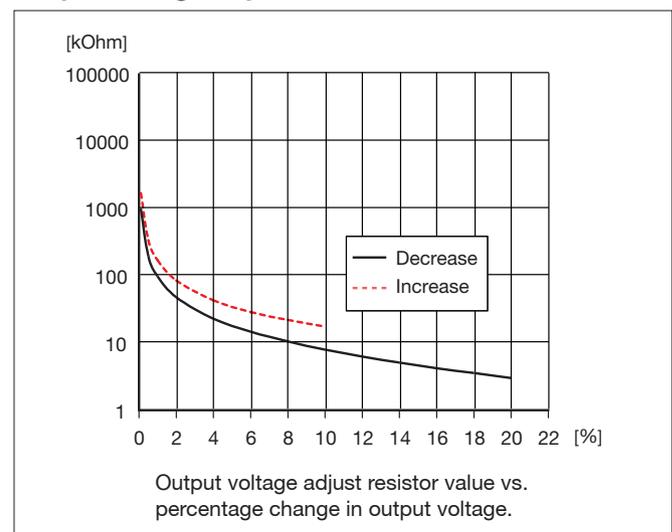
Eg Increase 4% $\Rightarrow V_{out} = 3.432\text{ V}_{dc}$

$$3.3 (100+4) / 1.225 \times 4 - 100 + 2 \times 4 / 4 = 43.04 \text{ kOhm}$$

Eg Decrease 2% $\Rightarrow V_{out} = 3.234\text{ V}_{dc}$

$$100 / 2 - 2 = 48.00 \text{ kOhm}$$

Output Voltage Adjust



$T_{Pcb} = -30...+90^{\circ}C$, $V_I = 36 ...75V$, sense pins connected to output pins unless otherwise specified.

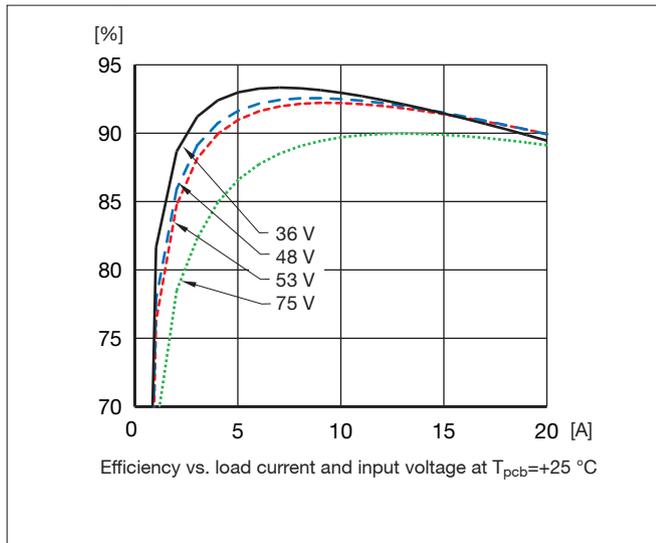
| Characteristics | | Conditions | Output | | | Unit |
|-----------------|---|--|--------|-----------|------|-------------------|
| | | | min | typ | max | |
| V_{O_i} | Output voltage initial setting and accuracy | $T_{Pcb} = +25^{\circ}C$, $V_I = 53 V$, $I_O = I_{Omax}$ | 4.96 | 5.00 | 5.04 | V |
| | Output adjust range | $I_O = I_{Omax}$ | 4.00 | | 5.50 | V |
| V_O | Output voltage tolerance band | $I_O = 0.1...1 \times I_{Omax}$ | 4.94 | | 5.06 | V |
| | Idling voltage | $I_O = 0$ | 4.94 | | 5.06 | V |
| | Line regulation | $I_O = I_{Omax}$ | | | 5 | mV |
| | Load regulation | $V_I = 53 V$, $I_O = 0.01...1 \times I_{Omax}$ | | | 5 | mV |
| V_{tr} | Load transient voltage deviation | $I_O = 0.1...1 \times I_{Omax}$, $V_I = 53 V$ Load step = $0.5 \times I_{Omax}$ di/dt = $1A/\mu s$ | | ± 300 | | mV |
| t_{tr} | Load transient recovery time | $I_O = 0.1...1 \times I_{Omax}$, $V_I = 53$ loadstep = $0.5 \times I_{Omax}$ | | 100 | | μs |
| t_r | Ramp-up time | $I_O = 0.1...0.9 \times V_O$ | | 15 | 30 | ms |
| t_s | Start-up time | From V_I connected to $V_O = 0.9 \times V_{O_i}$ | | 20 | 40 | ms |
| I_O | Output current | | 0 | | 20 | A |
| P_{Omax} | Max output power | At $V_O = V_{Onom}$ | 100 | | | W |
| I_{lim} | Current limit threshold | $T_{Pcb} < T_{Pcbmax}$ | | 23 | | A |
| I_{sc} | Short circuit current | $T_{Pcb} = 25^{\circ}C$ | | 27 | | A |
| V_{Oac} | Output ripple & noise | See ripple and noise, $I_O = I_{Omax}$ | | 110 | 150 | mV _{p-p} |
| SVR | Supply voltage rejection (ac) | $f = 100$ Hz sinewave , $1 V_{p-p}$, $V_I = 53 V$ | | 70 | | dB |
| OVP | Over voltage protection | $V_I = 53 V$ | 6.0 | | 7.5 | V |

Miscellaneous

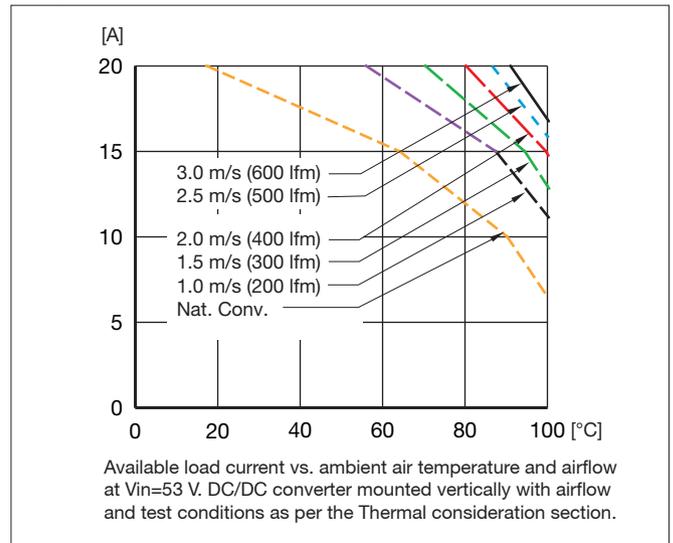
| Characteristics | | Conditions | min | typ | max | Unit |
|-----------------|------------------------|---|-----|------|-----|------|
| η | Efficiency - 50% load | $T_{Pcb} = +25^{\circ}C$, $V_I = 48 V$, $I_O = 0.5 \times I_{Omax}$ | | 92.5 | | % |
| η | Efficiency - 100% load | $T_{Pcb} = +25^{\circ}C$, $V_I = 48 V$, $I_O = I_{Omax}$ | | 90 | | % |
| η | Efficiency - 50% load | $T_{Pcb} = +25^{\circ}C$, $V_I = 53 V$, $I_O = 0.5 \times I_{Omax}$ | | 92 | | % |
| η | Efficiency - 100% load | $T_{Pcb} = +25^{\circ}C$, $V_I = 53 V$, $I_O = I_{Omax}$ | 87 | 89 | | % |
| P_d | Power Dissipation | $T_{Pcb} = +25^{\circ}C$, $V_I = 53 V$, $I_O = I_{Omax}$ | | 12 | | W |
| f_s | Switching frequency | $I_O = 0 ... 1.0 \times I_{Omax}$ | | 140 | | kHz |
| I_{Imax} | Maximum input current | $1.1 \times V_{O_i} \times I_{Omax} / \eta / V_{Imin}$ | | 3.4 | | A |

PKJ 4111E PI Typical Characteristics

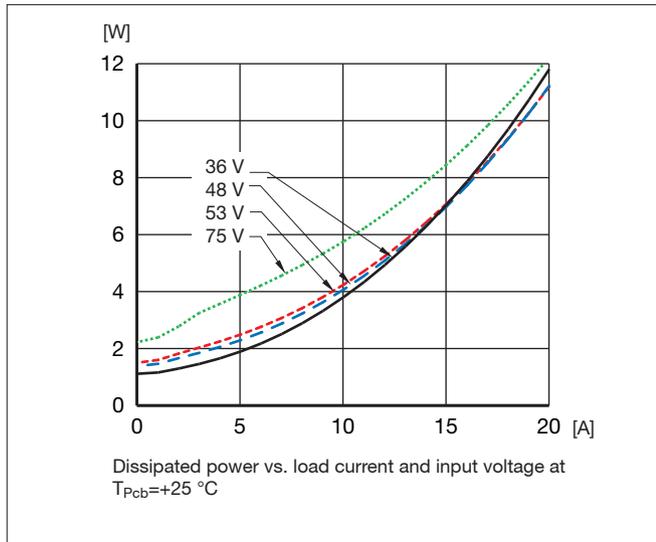
Efficiency



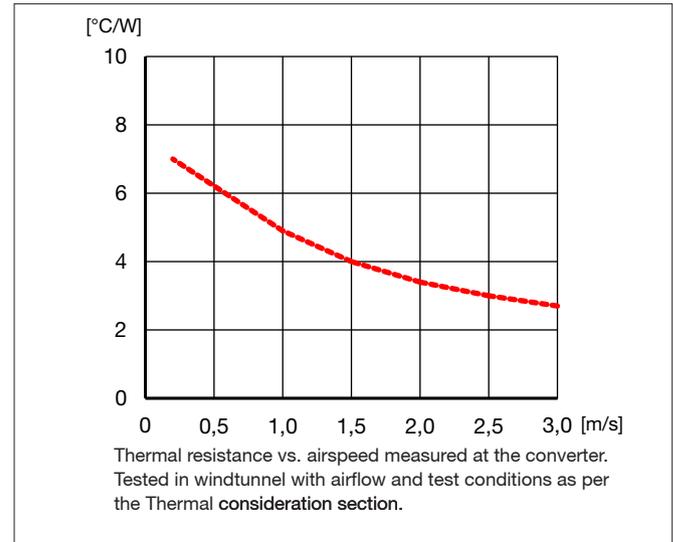
Output Current Derating



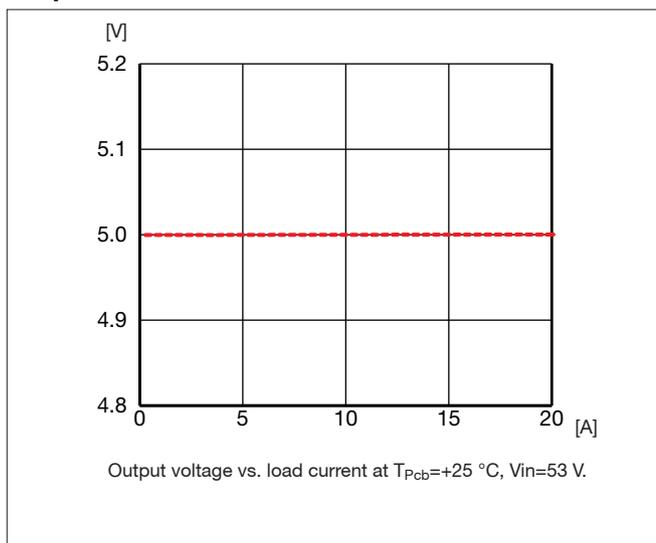
Power Dissipation



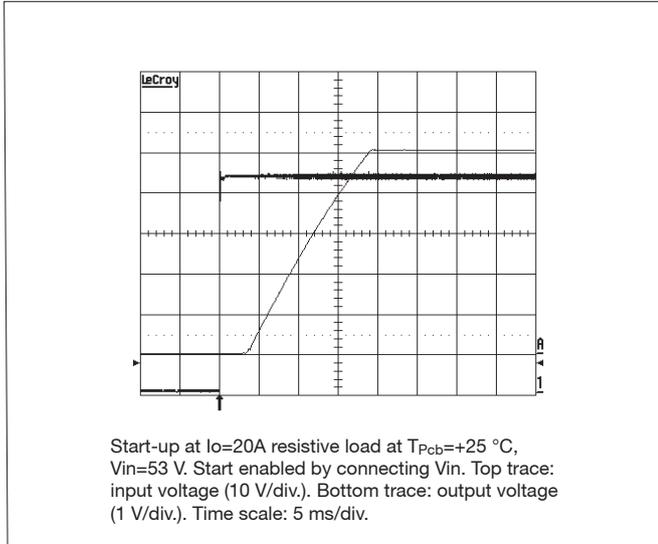
Thermal Resistance



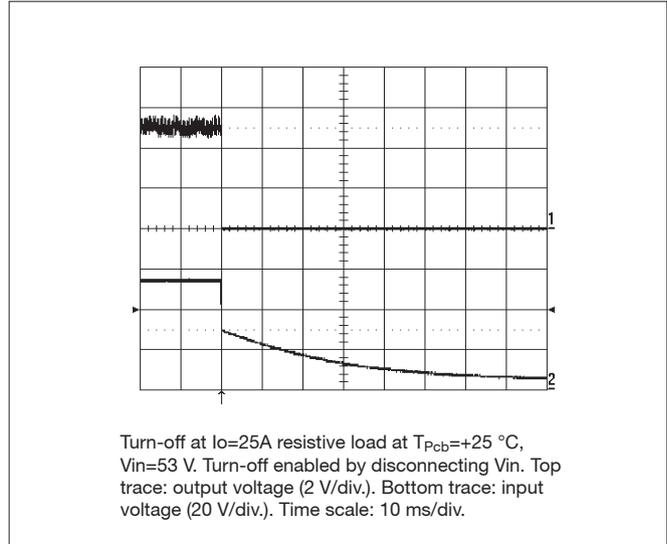
Output Characteristic



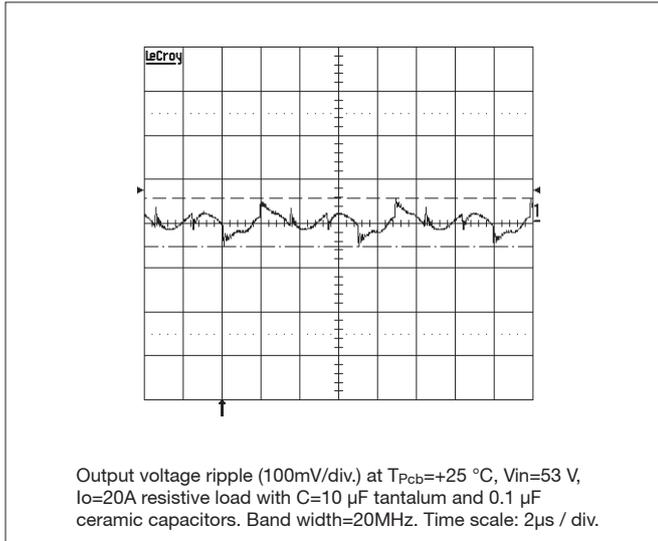
Start-Up



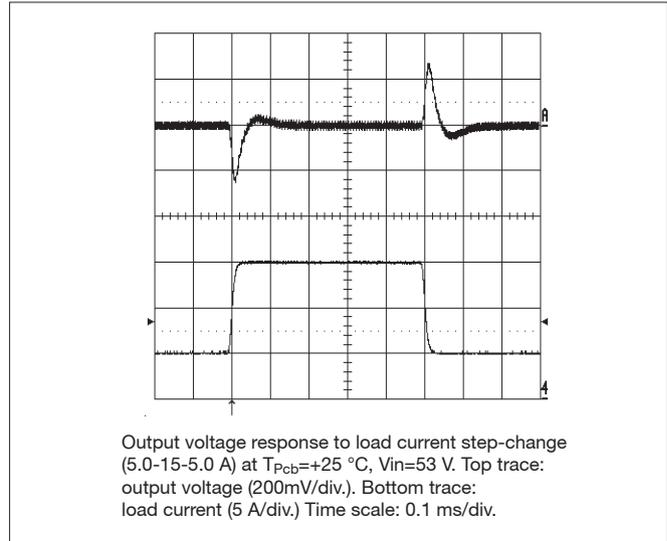
Turn-Off



Output Ripple



Transient



Output Voltage Adjust

The resistor value for an adjusted output voltage is calculated by using the following equations:

Output Voltage Adjust Upwards, Increase:

$$R_{adj} = [5.0(100+\Delta\%)/1.225\Delta\% - (100+2\Delta\%)/\Delta\%] \text{ k}\Omega$$

Output Voltage Adjust Downwards, Decrease:

$$R_{adj} = [(100/\Delta\% - 2)] \text{ k}\Omega$$

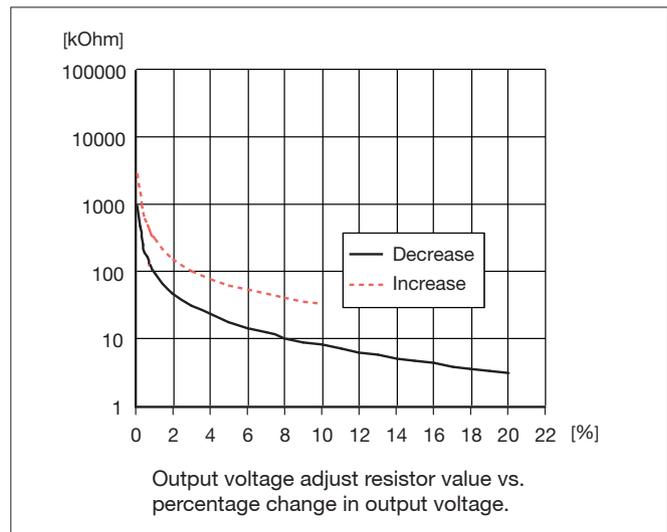
Eg Increase 4% => $V_{out} = 5.200\text{ }V_{dc}$

$$5.0(100+4)/1.225 \times 4 - 100 + 2 \times 4 / 4 = 79.12 \text{ k}\Omega$$

Eg Decrease 2% => $V_{out} = 4.900\text{ }V_{dc}$

$$100/2 - 2 = 48.00 \text{ k}\Omega$$

Output Voltage Adjust



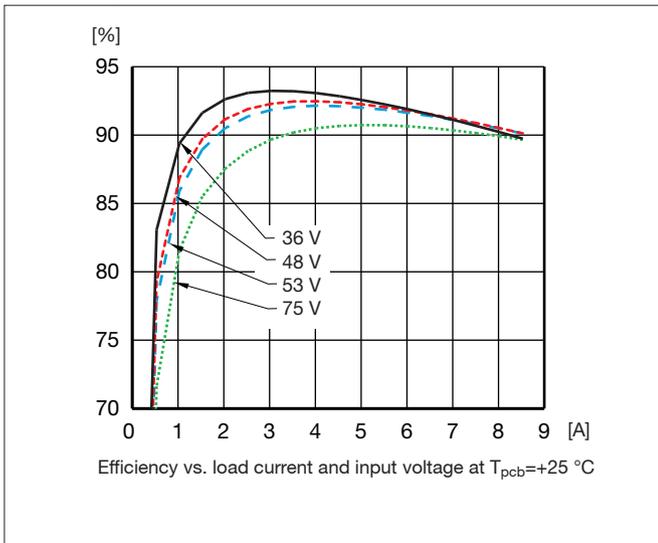
$T_{Pcb} = -30...+90^{\circ}C$, $V_I = 36 ...75V$, sense pins connected to output pins unless otherwise specified.

| Characteristics | | Conditions | Output | | | Unit |
|-----------------|---|--|--------|-----------|-------|-------------------|
| | | | min | typ | max | |
| V_{OI} | Output voltage initial setting and accuracy | $T_{Pcb} = +25^{\circ}C$, $V_I = 53 V$, $I_O = I_{Omax}$ | 11.88 | 12.0 | 12.12 | V |
| | Output adjust range | $I_O = I_{Omax}$ | 9.60 | | 13.20 | V |
| V_O | Output voltage tolerance band | $I_O = 0.1...1 \times I_{Omax}$ | 11.82 | | 12.18 | V |
| | Idling voltage | $I_O = 0$ | 11.82 | | 12.18 | V |
| | Line regulation | $I_O = I_{Omax}$ | | | 10 | mV |
| | Load regulation | $V_I = 53 V$, $I_O = 0.01...1 \times I_{Omax}$ | | | 10 | mV |
| V_{tr} | Load transient voltage deviation | $I_O = 0.1...1 \times I_{Omax}$, $V_I = 53 V$ Load step = $0.5 \times I_{Omax}$ di/dt = $1A/\mu s$ | | ± 400 | | mV |
| t_{tr} | Load transient recovery time | $I_O = 0.1...1 \times I_{Omax}$, $V_I = 53$ loadstep = $0.5 \times I_{Omax}$ | | 100 | | μs |
| t_r | Ramp-up time | $I_O = 0.1...0.9 \times V_O$ | | 15 | 30 | ms |
| t_s | Start-up time | From V_I connected to $V_O = 0.9 \times V_{OI}$ | | 20 | 40 | ms |
| I_O | Output current | | 0 | | 8.33 | A |
| P_{Omax} | Max output power | At $V_O = V_{Onom}$ | 100 | | | W |
| I_{lim} | Current limit threshold | $T_{Pcb} < T_{Pcbmax}$ | | 9.5 | | A |
| I_{sc} | Short circuit current | $T_{Pcb} = 25^{\circ}C$ | | 11.5 | | A |
| V_{Oac} | Output ripple & noise | See ripple and noise, $I_O = I_{Omax}$ | | 100 | 150 | mV _{p-p} |
| SVR | Supply voltage rejection (ac) | f = 100 Hz sinewave, 1 V _{p-p} , $V_I = 53 V$ | | 60 | | dB |
| OVP | Over voltage protection | $V_I = 53 V$ | 16 | | 18 | V |

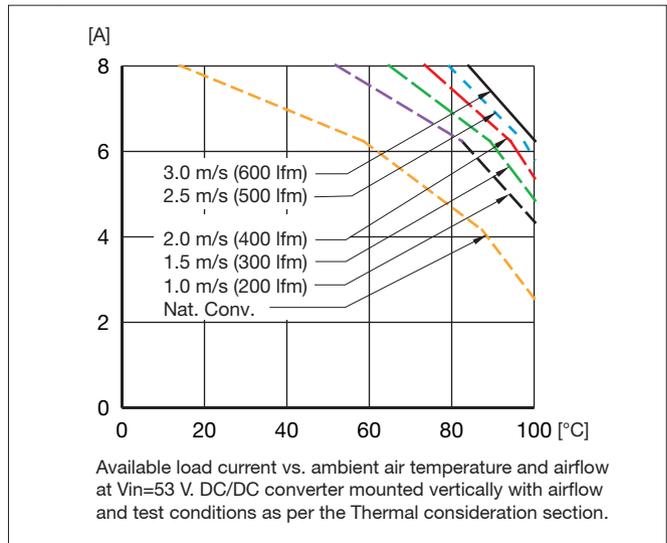
Miscellaneous

| Characteristics | | Conditions | min | typ | max | Unit |
|-----------------|------------------------|---|-----|------|-----|------|
| η | Efficiency - 50% load | $T_{Pcb} = +25^{\circ}C$, $V_I = 48 V$, $I_O = 0.5 \times I_{Omax}$ | | TBD | | % |
| η | Efficiency - 100% load | $T_{Pcb} = +25^{\circ}C$, $V_I = 48 V$, $I_O = I_{Omax}$ | | TBD | | % |
| η | Efficiency - 50% load | $T_{Pcb} = +25^{\circ}C$, $V_I = 53 V$, $I_O = 0.5 \times I_{Omax}$ | | 92.5 | | % |
| η | Efficiency - 100% load | $T_{Pcb} = +25^{\circ}C$, $V_I = 53 V$, $I_O = I_{Omax}$ | 88 | 90 | | % |
| P_d | Power Dissipation | $T_{Pcb} = +25^{\circ}C$, $V_I = 53 V$, $I_O = I_{Omax}$ | | 11.2 | | W |
| f_s | Switching frequency | $I_O = 0 ... 1.0 \times I_{Omax}$ | | 220 | | kHz |
| I_{Imax} | Maximum input current | $1.1 \times V_{OI} \times I_{Omax} / \eta / V_{Imin}$ | | 3.4 | | A |

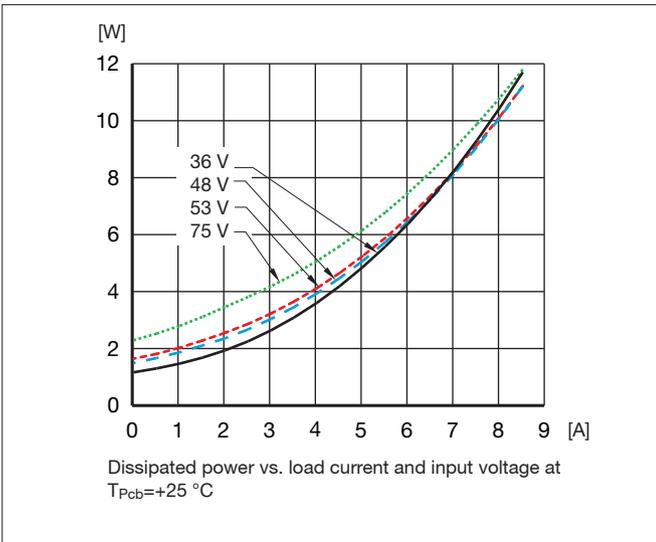
Efficiency



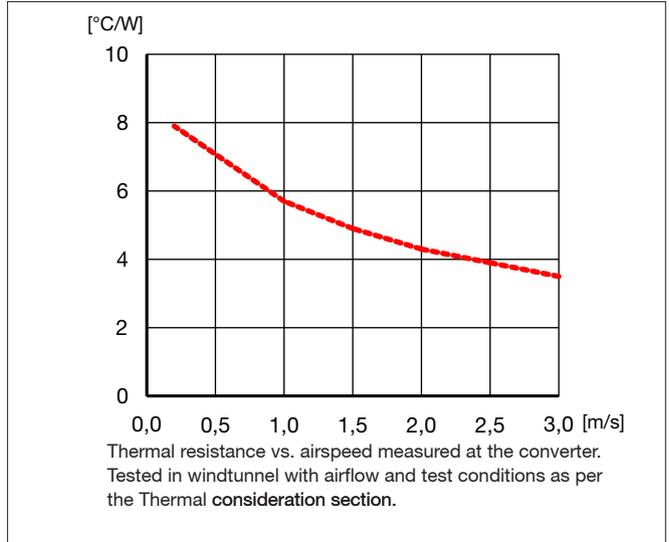
Output Current Derating



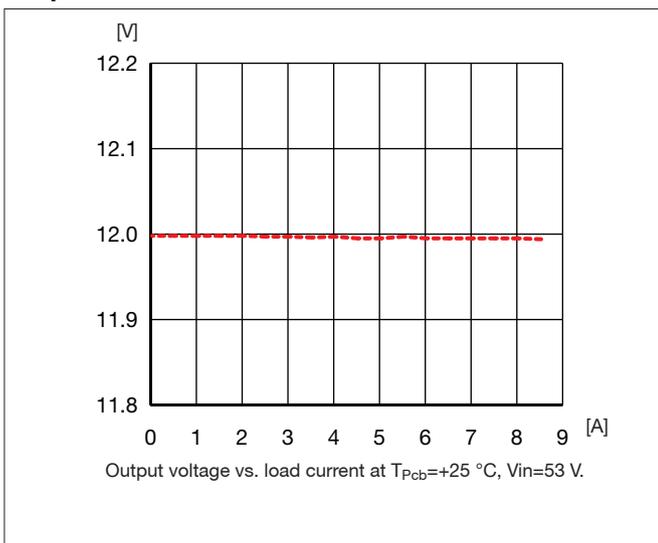
Power Dissipation



Thermal Resistance

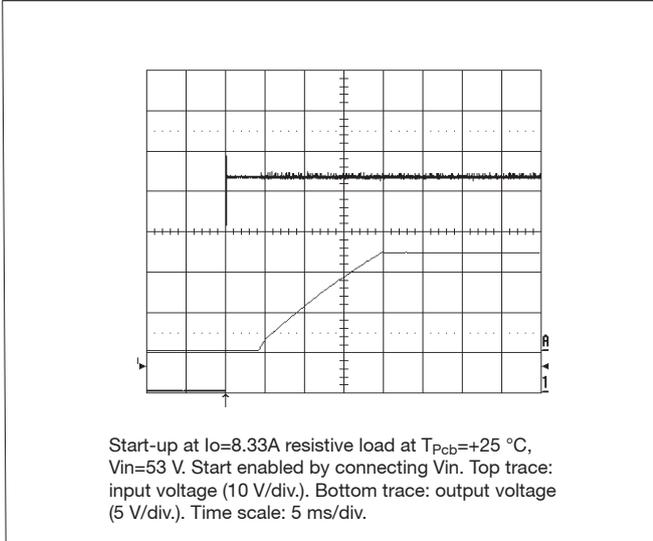


Output Characteristic

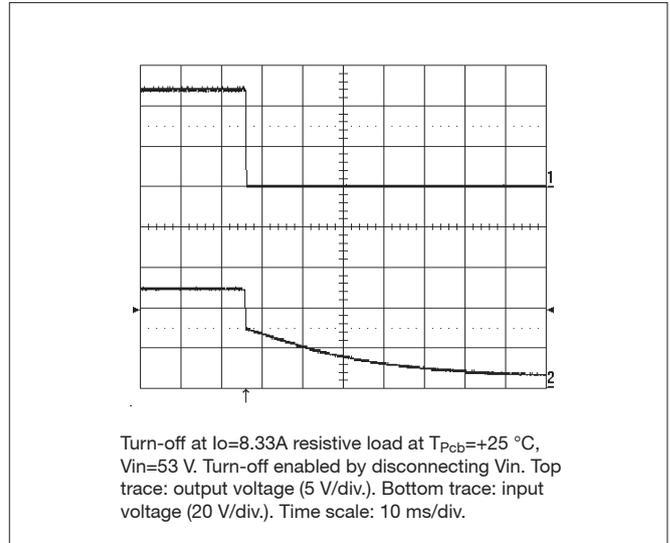


PKJ 4113E PI Typical Characteristics

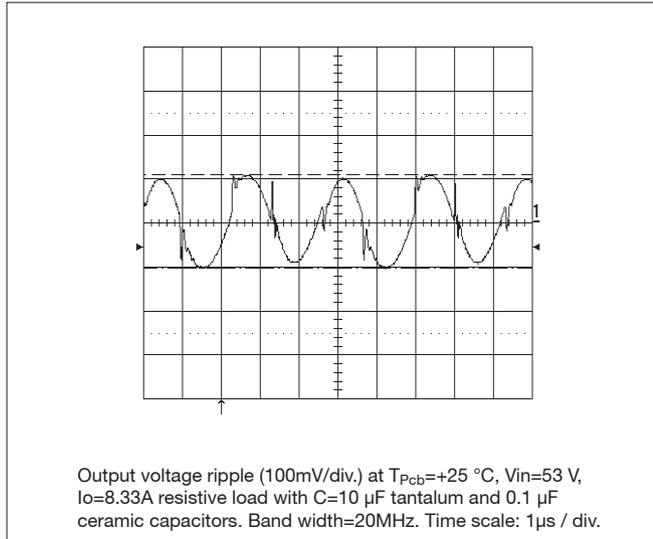
Start-Up



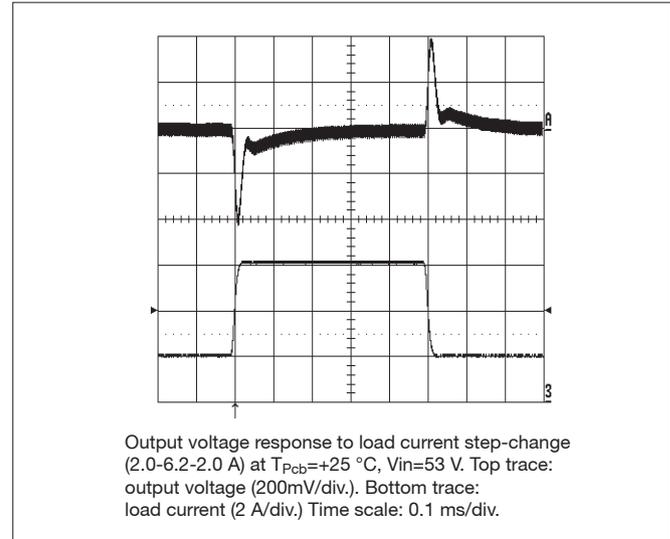
Turn-Off



Output Ripple



Transient



Output Voltage Adjust

The resistor value for an adjusted output voltage is calculated by using the following equations:

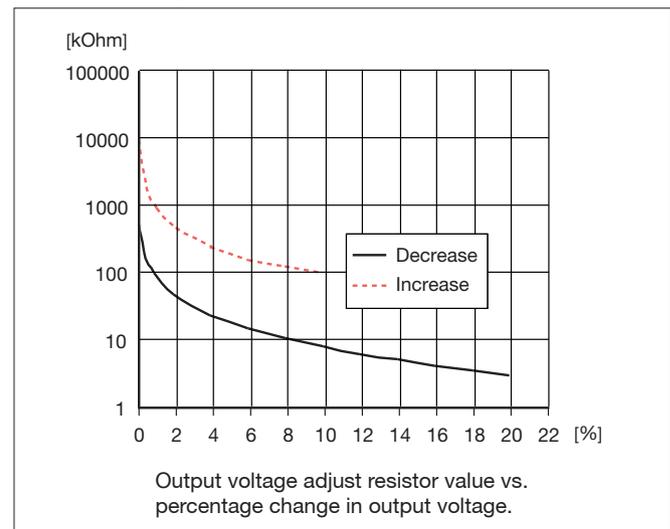
Output Voltage Adjust Upwards, Increase:
 $R_{adj} = [12(100+\Delta\%) / 1.225\Delta\% - (100+2\Delta\%) / \Delta\%] \text{ k}\Omega$

Output Voltage Adjust Downwards, Decrease:
 $R_{adj} = [(100 / \Delta\% - 2)] \text{ k}\Omega$

Eg Increase 4% $\Rightarrow V_{out} = 12.48 V_{dc}$
 $12(100+4) / 1.225 \times 4 - 100 + 2 \times 4 / 4 = 228 \text{ k}\Omega$

Eg Decrease 2% $\Rightarrow V_{out} = 11.76 V_{dc}$
 $100 / 2 - 2 = 48.00 \text{ k}\Omega$

Output Voltage Adjust



$T_{Pcb} = -30...+90^{\circ}C$, $V_I = 36 ...75V$, sense pins connected to output pins unless otherwise specified.

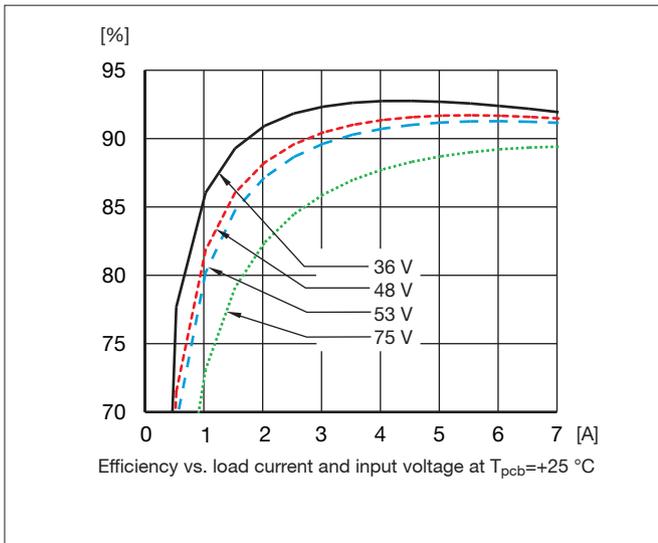
| Characteristics | | Conditions | Output | | | Unit |
|-----------------|---|--|--------|-----------|-------|-------------------|
| | | | min | typ | max | |
| V_{O_i} | Output voltage initial setting and accuracy | $T_{Pcb} = +25^{\circ}C$, $V_I = 53 V$, $I_O = I_{Omax}$ | 14.85 | 15.0 | 15.15 | V |
| | Output adjust range | $I_O = I_{Omax}$ | 12.0 | | 16.5 | V |
| V_O | Output voltage tolerance band | $I_O = 0.1...1 \times I_{Omax}$ | 14.77 | | 15.23 | V |
| | Idling voltage | $I_O = 0$ | 14.77 | | 15.23 | V |
| | Line regulation | $I_O = I_{Omax}$ | | | 10 | mV |
| | Load regulation | $V_I = 53 V$, $I_O = 0.01...1 \times I_{Omax}$ | | | 10 | mV |
| V_{tr} | Load transient voltage deviation | $I_O = 0.1...1 \times I_{Omax}$, $V_I = 53 V$ Load step = $0.5 \times I_{Omax}$ di/dt = $1A/\mu s$ | | ± 350 | | mV |
| t_{tr} | Load transient recovery time | $I_O = 0.1...1 \times I_{Omax}$, $V_I = 53$ loadstep = $0.5 \times I_{Omax}$ | | 100 | | μs |
| t_r | Ramp-up time | $I_O = 0.1...0.9 \times V_O$ | | 15 | 30 | ms |
| t_s | Start-up time | From V_I connected to $V_O = 0.9 \times V_{O_i}$ | | 20 | 40 | ms |
| I_O | Output current | | 0 | | 6.67 | A |
| P_{Omax} | Max output power | At $V_O = V_{Onom}$ | 100 | | | W |
| I_{lim} | Current limit threshold | $T_{Pcb} < T_{Pcbmax}$ | | 7.5 | | A |
| I_{sc} | Short circuit current | $T_{Pcb} = 25^{\circ}C$ | | 10.5 | | A |
| V_{Oac} | Output ripple & noise | See ripple and noise, $I_O = I_{Omax}$ | | 110 | 150 | mV _{p-p} |
| SVR | Supply voltage rejection (ac) | $f = 100$ Hz sinewave , $1 V_{p-p}$, $V_I = 53 V$ | | 65 | | dB |
| OVP | Over voltage protection | $V_I = 53 V$ | 21 | | 23 | V |

Miscellaneous

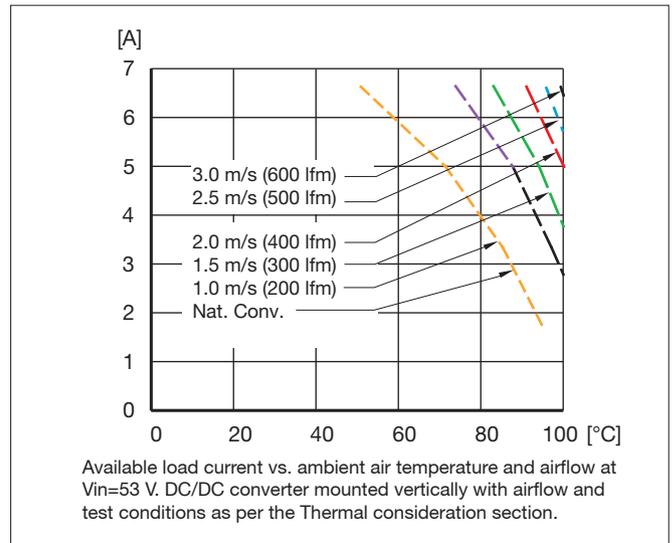
| Characteristics | | Conditions | min | typ | max | Unit |
|-----------------|------------------------|---|-----|------|-----|------|
| η | Efficiency - 50% load | $T_{Pcb} = +25^{\circ}C$, $V_I = 48 V$, $I_O = 0.5 \times I_{Omax}$ | | 91.0 | | % |
| η | Efficiency - 100% load | $T_{Pcb} = +25^{\circ}C$, $V_I = 48 V$, $I_O = I_{Omax}$ | | 91.6 | | % |
| η | Efficiency - 50% load | $T_{Pcb} = +25^{\circ}C$, $V_I = 53 V$, $I_O = 0.5 \times I_{Omax}$ | | 90.2 | | % |
| η | Efficiency - 100% load | $T_{Pcb} = +25^{\circ}C$, $V_I = 53 V$, $I_O = I_{Omax}$ | 89 | 91.2 | | % |
| P_d | Power Dissipation | $T_{Pcb} = +25^{\circ}C$, $V_I = 53 V$, $I_O = I_{Omax}$ | | 9.5 | | W |
| f_s | Switching frequency | $I_O = 0 ... 1.0 \times I_{Omax}$ | | 220 | | kHz |
| I_{Imax} | Maximum input current | $1.1 \times V_{O_i} \times I_{Omax} / \eta / V_{Imin}$ | | 3.3 | | A |

PKJ 4115E PI Typical Characteristics

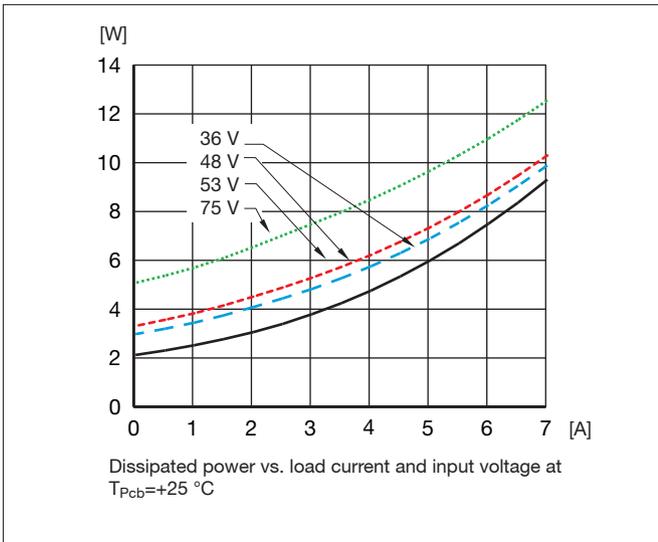
Efficiency



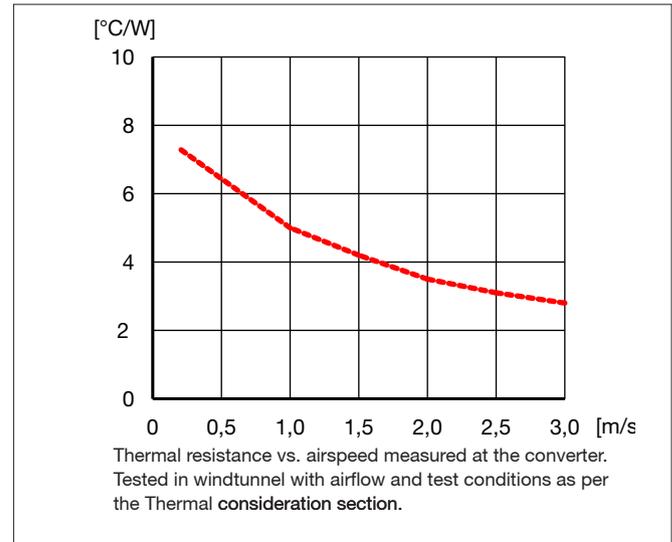
Output Current Derating



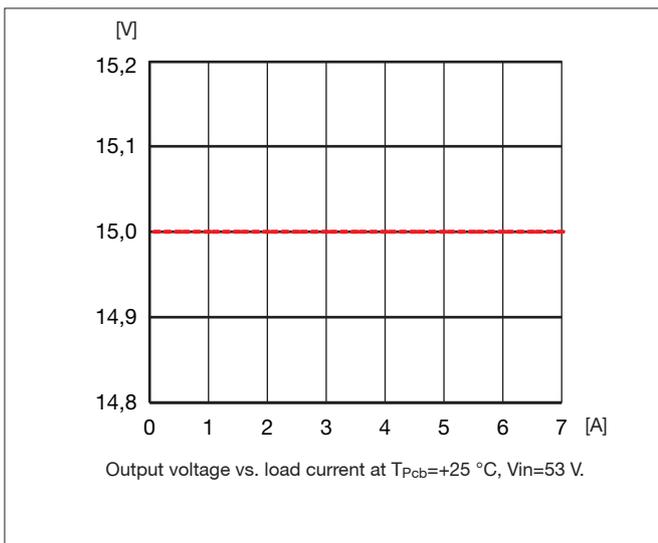
Power Dissipation



Thermal Resistance

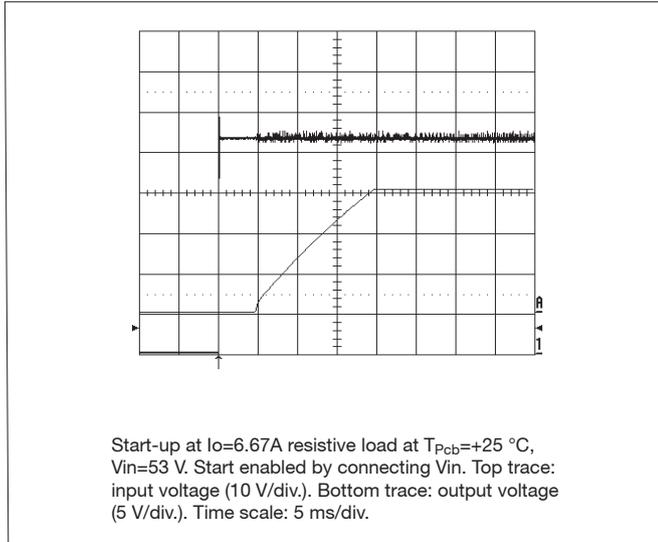


Output Characteristic

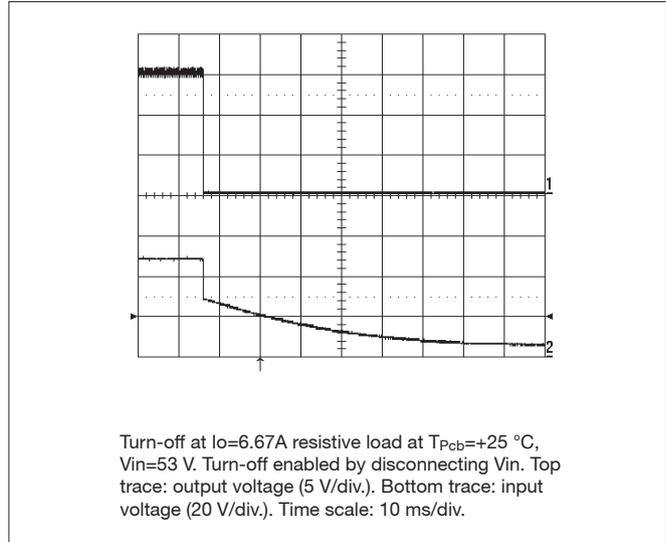


PKJ 4115E PI Typical Characteristics

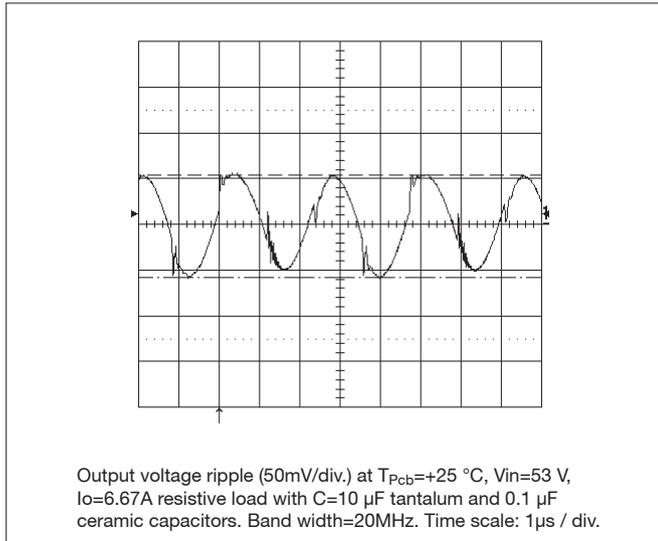
Start-Up



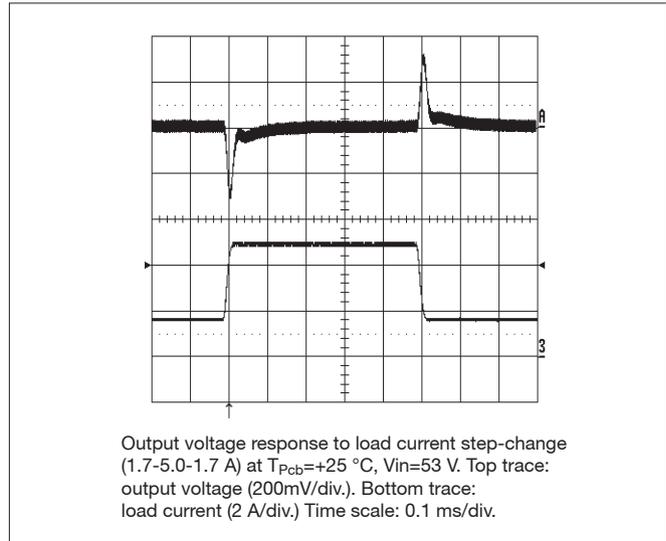
Turn-Off



Output Ripple



Transient



Output Voltage Adjust

The resistor value for an adjusted output voltage is calculated by using the following equations:

Output Voltage Adjust Upwards, Increase:

$$R_{adj} = [15(100+\Delta\%)/1.225\Delta\% - (100+2\Delta\%)/\Delta\%] \text{ kOhm}$$

Output Voltage Adjust Downwards, Decrease:

$$R_{adj} = [(100/\Delta\%-2)] \text{ kOhm}$$

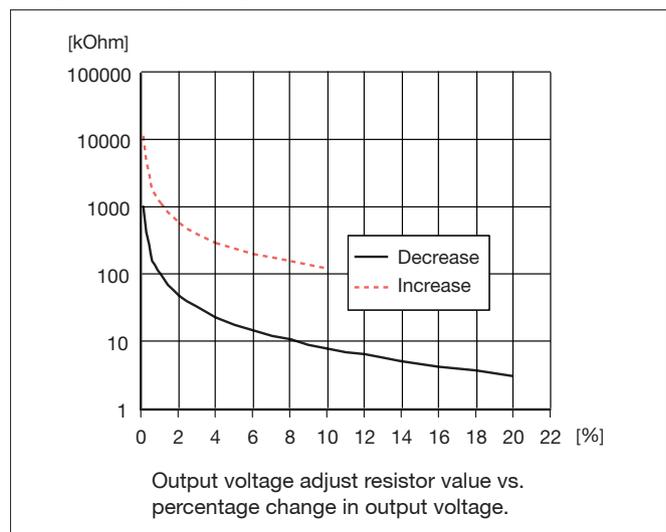
Eg Increase 4% $\Rightarrow V_{out} = 15.60\text{ V}_{dc}$

$$15 (100+4)/1.225 \times 4 - 100 + 2 \times 4 / 4 = 291 \text{ kOhm}$$

Eg Decrease 2% $\Rightarrow V_{out} = 14.70\text{ V}_{dc}$

$$100/2-2=48.00 \text{ kOhm}$$

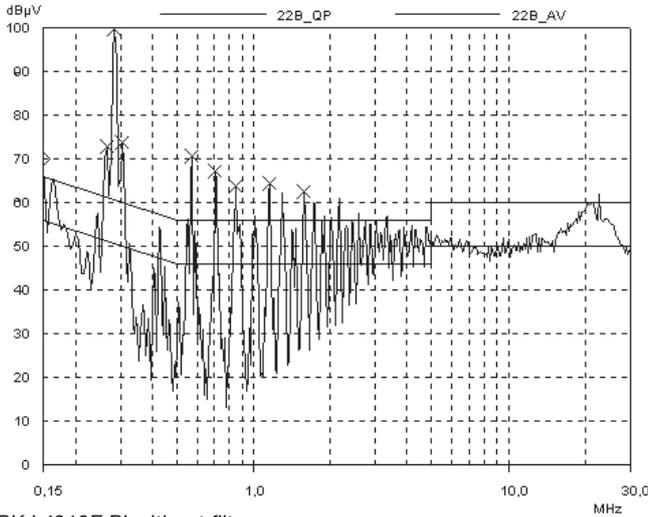
Output Voltage Adjust



EMC Specification

The conducted EMI measurement was performed using a module placed directly on the test bench.
 The fundamental switching frequency is 140kHz for PKJ 4810E PI @ $V_I = 53V$, $I_O = (0.1...1.0) \times I_{Omax}$.

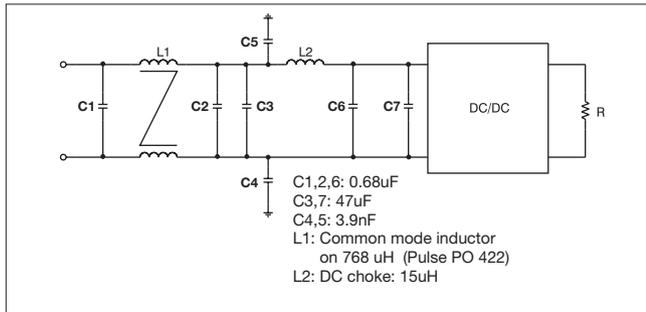
Conducted EMI Input terminal value (typ)



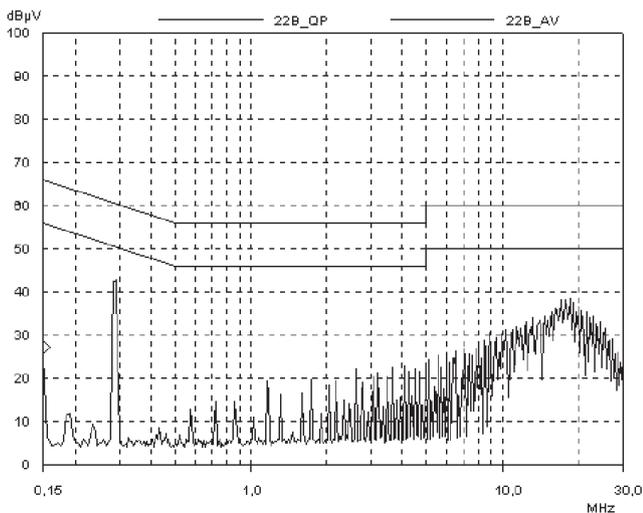
PKJ 4810E PI without filter.

External filter (class B)

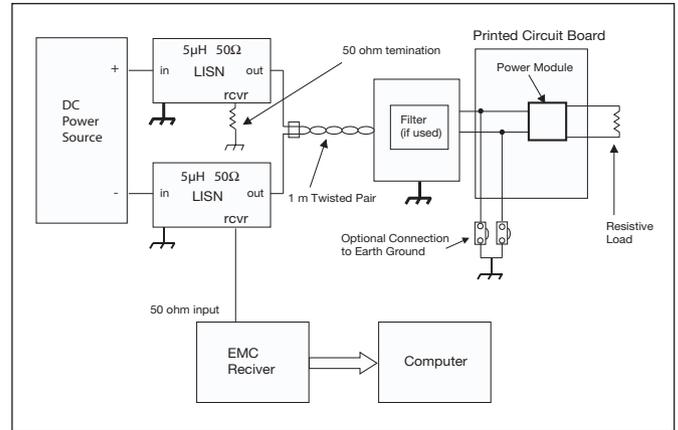
Required external input filter in order to meet class B in EN 55022, CISPR 22 and FCC part 15J.



The capacitors are ceramic type. Low ESR is critical for achieving these results.



PKJ 4810E PI with filter.



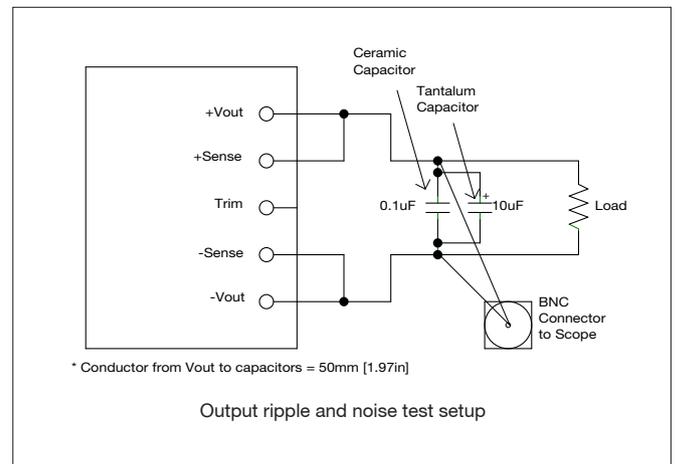
Test set-up.

Layout Recommendation

The radiated EMI performance of the DC/DC converter will be optimised by including a ground plane in the PCB area under the DC/DC converter. This approach will return switching noise to ground as directly as possible, with improvements to both emissions and susceptibility. If one ground trace is used, it should be connected to the input return. Alternatively, two ground traces may be used, with the trace under the input side of the DC/DC converter connected to the input return and the trace under the output side of the DC/DC converter connected to the output return. Make sure to use appropriate safety isolation spacing between these two return traces. The use of two traces as described will provide the capability of routing the input noise and output noise back to their respective returns.

Output ripple and noise

The circuit below has been used for the ripple and noise measurements on the PKJ 4000E Series DC/DC converters.



Operating Information

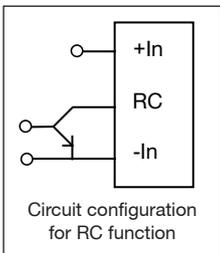
Input Voltage

The input voltage range 36...75Vdc meets the requirements of the European Telecom Standard ETS 300 132-2 for normal input voltage range in -48V and -60V DC systems, -40.5...-57.0V and -50.0...-72V respectively. At input voltages exceeding 75V, the power loss will be higher than at normal input voltage and T_{Pcb} must be limited to absolute max +125°C. The absolute maximum continuous input voltage is 80Vdc.

Turn-Off Input Voltage

The PKJ 4000E Series DC/DC converters monitor the input voltage and will turn on and turn off at predetermined levels. The minimum hysteresis between turn on and turn off input voltage is 1V where the turn on input voltage is the highest.

Remote Control (RC)



The PKJ 4000E Series DC/DC converters have a remote control function referenced to the primary side (- In), with negative and positive logic options available. The RC function allows the converter to be turned on/off by an external device like a semiconductor or mechanical switch. The RC pin has an internal

pull up resistor to + In. The needed maximum sink current is 1mA. When the RC pin is left open, the voltage generated on the RC pin is 3.5-6.0V. The maximum allowable leakage current of the switch is 50µA.

The standard converter is provided with “negative logic” remote control and the converter will be off until the RC pin is connected to the - In. To turn on the converter the voltage between RC pin and - In should be less than 1V. To turn off the converter the RC pin should be left open, or connected to a voltage higher than 4V referenced to - In. In situations where it is desired to have the converter to power up automatically without the need for control signals or a switch, the RC pin can be wired directly to - In.

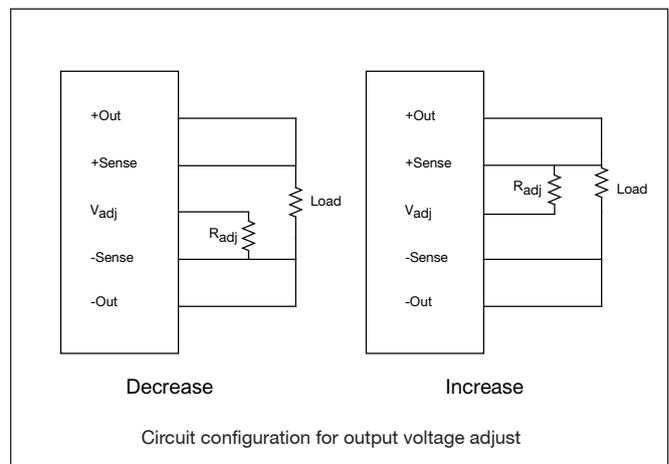
The second option is “positive logic” remote control, which can be ordered by adding the suffix “P” to the end of the part number. The converter will turn on when the input voltage is applied with the RC pin open. Turn off is achieved by connecting the RC pin to the - In. To ensure safe turn off the voltage difference between RC pin and the - In pin shall be less than 1V. The converter will restart automatically when this connection is opened.

Remote Sense

All PKJ 4000E Series DC/DC converters have remote sense that can be used to compensate for moderate amounts of resistance in the distribution system and allow for voltage regulation at the load or other selected point. The remote sense lines will carry very little current and do not need a large cross sectional area. However, the sense lines on the PCB should be located close to a ground trace or ground plane. In a discrete wiring situation, the use of twisted pair wires or other technique to reduce noise susceptibility is highly recommended. The remote sense circuitry will compensate for up to 10% voltage drop between the sense voltage and the voltage at the output pins. The output voltage and the remote sense voltage offset must be less than the minimum over voltage trip point. If the remote sense is not needed the -Sense should be connected to -Out and +Sense should be connected to +Out.

Output Voltage Adjust (V_{adj})

All PKJ 4000E Series DC/DC converters have an Output Voltage adjust pin (V_{adj}). This pin can be used to adjust the output voltage above or below Output voltage initial setting. When increasing the output voltage, the voltage at the output pins (including any remote sense offset) must be kept below the overvoltage trip point, to prevent the converter from shut down. Also note that at increased output voltages the maximum power rating of the converter remains the same, and the output current capability will decrease correspondingly. To decrease the output voltage the resistor should be connected between V_{adj} pin and -Sense pin. To increase the voltage the resistor should be connected between V_{adj} pin and +Sense pin. The resistor value of the Output voltage adjust function is according to information given under the output section.



Operating Information

Current Limit Protection

The PKJ 4000E Series DC/DC converters include current limiting circuitry that allows them to withstand continuous overloads or short circuit conditions on the output. The output voltage will decrease towards zero for output currents in excess of max output current (I_{omax}).

The converter will resume normal operation after removal of the overload. The load distribution system should be designed to carry the maximum output short circuit current specified.

Over Voltage Protection (OVP)

The PKJ 4000E Series DC/DC converters have latching output overvoltage protection. In the event of an overvoltage condition, the converter will shut down immediately. The converter can be restarted by cycling the input voltage or using the remote control function.

Over Temperature Protection (OTP)

The PKJ 4000E Series DC/DC converters are protected from thermal overload by an internal over temperature shutdown circuit. When the PCB temperature (centre of PCB) exceeds 135 °C the converter will shut down immediately (latching). The converter can be restarted by cycling the input voltage or using the remote control function.

Input And Output Impedance

The impedance of both the power source and the load will interact with the impedance of the DC/DC converter. It is most important to have a ratio between L and C as low as possible, i.e. a low characteristic impedance, both at the input and output, as the converters have a low energy storage capability. The PKJ 4000E Series DC/DC converters have been designed to be completely stable without the need for external capacitors on the input or the output circuits. The performance in some applications can be enhanced by addition of external capacitance as described under maximum capacitive load. If the distribution of the input voltage source to the converter contains significant inductance, the addition of a 100µF capacitor across the input of the converter will help insure stability. This capacitor is not required when powering the DC/DC converter from a low impedance source with short, low inductance, input power leads.

Maximum Capacitive Load

When powering loads with significant dynamic current requirements, the voltage regulation at the load can be improved by addition of decoupling capacitance at the load. The most affective technique is to locate low ESR ceramic capacitors as close to the load as possible, using several capacitors to lower the effective ESR. These ceramic capacitors will handle short duration high-frequency components of dynamic load changes. In addition, higher values of electrolytic capacitors should be used to handle the mid-frequency components. It is equally important to use good design practise when configuring the DC distribution system.

Low resistance and low inductance PCB (printed circuit board) layouts and cabling should be used. Remember that when using remote sensing, all resistance, inductance and capacitance of the distribution system is within the feedback loop of the converter. This can affect on the converters compensation and the resulting stability and dynamic response performance. As a "rule of thumb", 100 µF/A of output current can be used without any additional analysis. For example with a 25A converter, values of decoupling capacitance up to 2500 µF can be used without regard to stability. With larger values of capacitance, the load transient recovery time can exceed the specified value. As much of the capacitance as possible should be outside the remote sensing loop and close to the load. The absolute maximum value of output capacitance is 10 000 µF. For values larger than this, please contact your local Ericsson Power Modules representative.

Parallel Operation

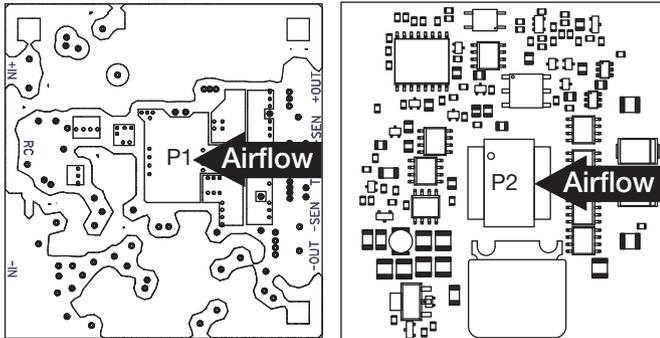
The PKJ 4000E Series DC/DC converters can be paralleled for redundancy if external "O"-ring diodes are used in series with the outputs. It is not recommended to parallel the PKJ 4000E Series DC/DC converters for increased power without using external current sharing circuits.

Thermal Consideration

General

The PKJ 4000E Series DC/DC converters are designed to operate in a variety of thermal environments, however sufficient cooling should be provided to help ensure reliable operation. Heat is removed by conduction, convection and radiation to the surrounding environment. Increased airflow enhances the heat transfer via convection. The available load current vs. ambient air temperature and airflow at $V_{in}=53\text{ V}$ for each model is according to the information given under the output section. The test is done in a wind tunnel with a cross section of 305x305mm, the DC/DC converter vertically mounted on a 8 layer PCB with a size of 254x254mm. Each layer with 35 μm (1oz) copper. Proper cooling can be verified by measuring the temperature of selected devices. Peak temperature can occur at position P1 and P2. The temperature at these positions should not exceed the recommended max values.

| Position | Device | $T_{critical}$ | Recommended Max Value |
|----------|-------------|----------------|-----------------------|
| P1 | FR4 PWB | $T_{surface}$ | 125°C |
| P2 | Transformer | T_{core} | 125°C |



Calculation of ambient temperature

By using the thermal resistance the maximum allowed ambient temperature can be calculated.

- The powerloss is calculated by using the formula $((1/\eta) - 1) \times \text{output power} = \text{power losses}$.
 η = efficiency of converter. E.g 89% = 0.89
- Find the value of the thermal resistance for each product in the diagram by using the airflow speed at the output section of the converter. Take the thermal resistance x powerloss to get the temperature increase.
- Max allowed calculated ambient temperature is: $\text{Max } T_{PCB} \text{ of DC/DC converter} - \text{temperature increase}$.

E.g PKJ 4810E PI at 1m/s:

A. $((\frac{1}{0.89}) - 1) \times 82.5\text{W} = 10.2\text{W}$

B. $10.2\text{W} \times 5.1^\circ\text{C/W} = 52^\circ\text{C}$

C. $125^\circ\text{C} - 52^\circ\text{C} = \text{max ambient temperature is } 73^\circ\text{C}$

The real temperature will be dependent on several factors, like PCB size and type, direction of airflow, air turbulence etc. It is recommended to verify the temperature by testing.

Miscellaneous

Soldering Information

The PKJ 4000E Series DC/DC converters are intended for through hole mounting on a PCB. When wave soldering is used max temperature on the pins are specified to 215°C for 10 seconds. Maximum preheat rate of 4°C/s is suggested. When hand soldering is used a thermocouple needs to be mounted on the DC/DC converter pins to verify that pin temperatures does not exceed 215°C for longer time than 10 seconds with the used soldering tools.

No-clean flux is recommended to avoid entrapment of cleaning fluids in cavities inside of the DC/DC power module. The residues may affect long time reliability and isolation voltage.

Delivery Package Information

PKJ 4000E series standard delivery package is a 50 pcs box (One box contains 5 full trays and 1 empty hold down tray).

Tray Specification

| | |
|-----------------------------|------------------|
| Material: | Polystyrene (PS) |
| Max surface resistance: | 10 MOhm/sq |
| Color: | Black |
| Capacity: | 10 pcs/tray |
| Loaded tray stacking pitch: | 15.3 mm |
| Weight: | 133 g |

Compatibility with RoHS requirements

The products are compatible with the relevant clauses and requirements of the RoHS directive 2002/95/EC and have a maximum concentration value of 0.1% by weight in homogeneous materials for lead, mercury, hexavalent chromium, PBB and PBDE and of 0.01% by weight in homogeneous materials for cadmium.

Exemptions in the RoHS directive utilized in Ericsson Power Modules products include:

- Lead in high melting temperature type solder (used to solder the die in semiconductor packages)
- Lead in glass of electronics components and in electronic ceramic parts (e.g. fill material in chip resistors)
- Lead as an alloying element in copper alloy containing up to 4% lead by weight (used in connection pins made of Brass)

Quality

15867339858

Reliability

The Mean Time Between Failure (MTBF) of the PKJ 4000E series DC/DC converter family is calculated to be greater than (>) 7.6 million hours at full output power and a PCB temperature of +110°C using the Ericsson failure rate data system (TILDA/Preditool). The Ericsson failure rate data system is based on field failure rates and is continuously updated. The data corresponds to actual failure rates of components used in Information Technology and Telecom equipment in temperature controlled environments ($T_A = -5...+65^\circ\text{C}$). The data is considered to have a confidence level of 90%. For more information please refer to Design Note 002.

Quality Statement

The PKJ 4000E series DC/DC converters are designed and manufactured in an industrial environment where quality systems and methods like ISO 9000, 6 σ (sigma), and SPC are intensively in use to boost the continuous improvements strategy. Infant mortality or early failures in the products are screened out and they are subjected to an ATE-based final test. Conservative design rules, design reviews and product qualifications, plus the high competence of an engaged work force, contribute to the high quality of our products.

Warranty

Warranty period and conditions are defined in Ericsson Power Modules General Terms and Conditions of Sale.

Limitation of Liability

Ericsson Power Modules does not make any other warranties, expressed or implied including any warranty of merchantability or fitness for a particular purpose (including, but not limited to, use in life support applications, where malfunctions of product can cause injury to a person's health or life).

Product Program

| V _I | V _O /I _O max | P _O max | Ordering No. | Comment |
|----------------|------------------------------------|--------------------|---------------|---|
| | Output 1 | | | |
| 48/60 | 1.5 V/40 A | 60 W | PKJ 4618HE PI | |
| 48/60 | 1.8 V/36 A | 65 W | PKJ 4618GE PI | |
| 48/60 | 2.5 V/30 A | 75.5 W | PKJ 4719E PI | |
| 48/60 | 3.3 V/25 A | 82.5 W | PKJ 4810E PI | |
| 48/60 | 3.3 V/30 A | 100 W | PKJ 4110E PI | See Technical Specification PKJ4110E PI |
| 48/60 | 5 V/20 A | 100 W | PKJ 4111E PI | |
| 48/60 | 12 V/8.3 A | 100 W | PKJ 4113E PI | |
| 48/60 | 15 V/6.7 A | 100 W | PKJ 4115E PI | |

The PKJE series DC/DC converter may be ordered with different options listed in the Product Options Table.

For more information about the complete product program, please refer to our website: www.ericsson.com/powermodules

Product Options

| Option | Suffix | Ordering No. |
|-------------------------------|--------|----------------|
| Positive Remote control logic | P | PKJ 4810E PIP |
| Pin length 3.6 mm (0.14 in) | LA | PKJ 4810E PILA |

Note: As an example a positive logic, short pin product would be PKJ 4810E PIPLA

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Datasheet

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